

# Homotopically trivializing the circle in the framed little disks

Gabriel C. Drummond-Cole

Northwestern University

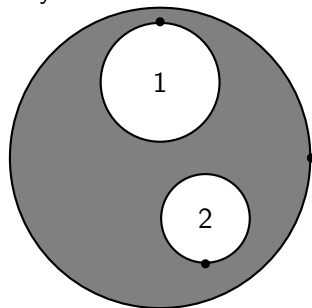
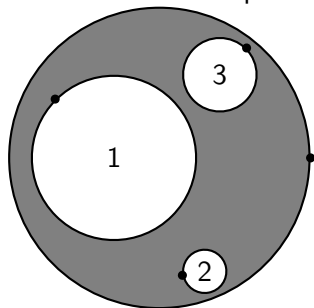
March 13, 2012

# The framed little disks

Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.

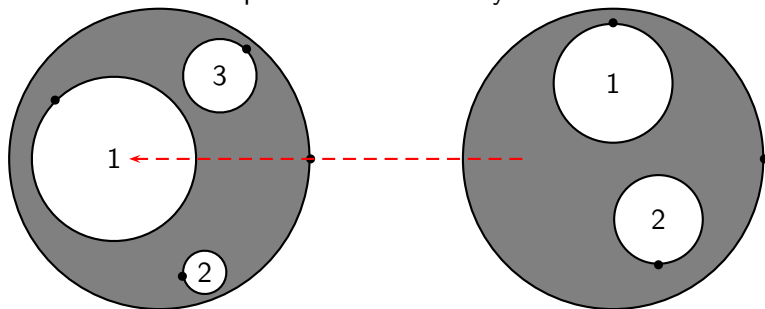
## The framed little disks

Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



## The framed little disks

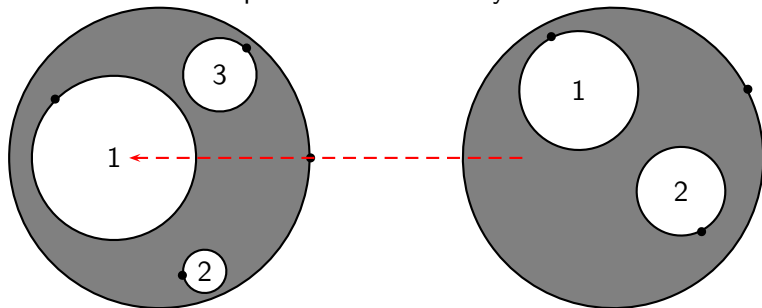
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

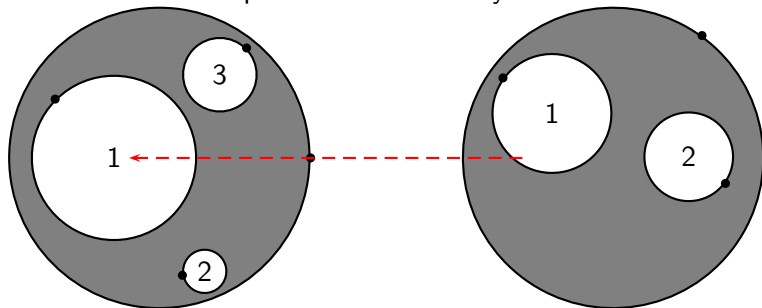
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

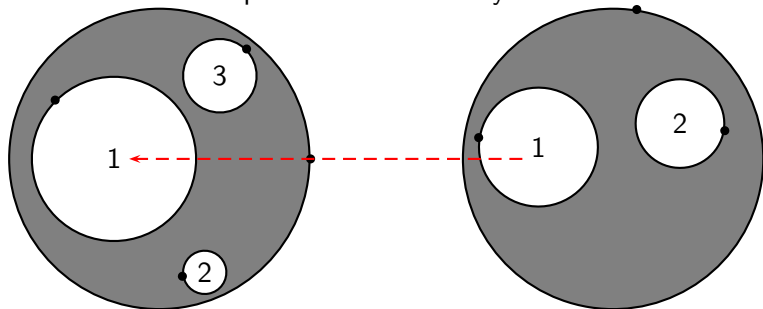
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

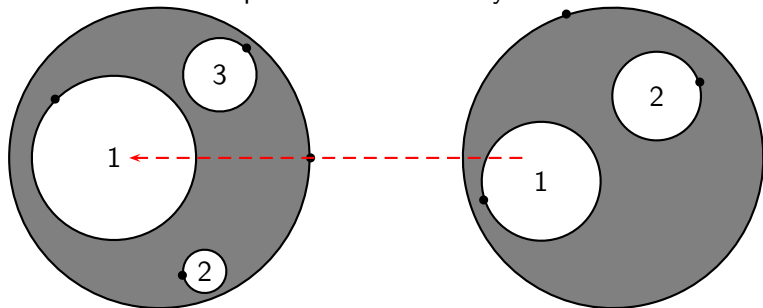
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.

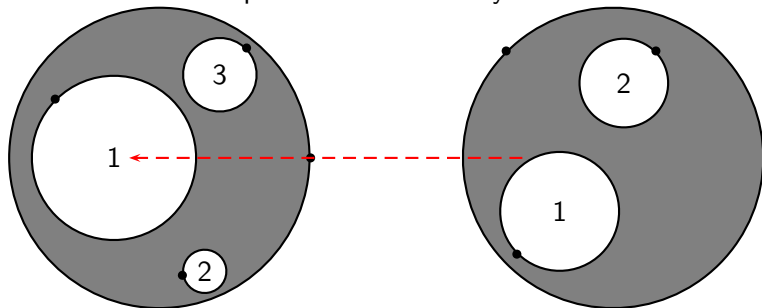


We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.



## The framed little disks

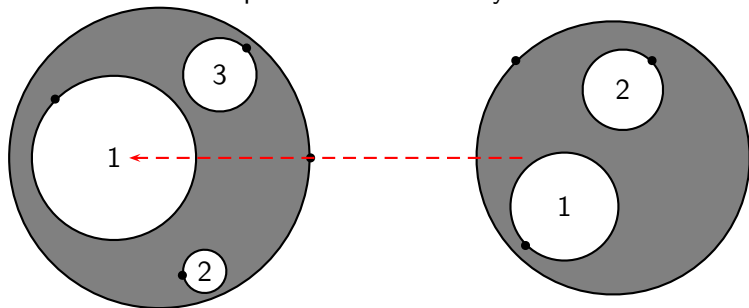
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

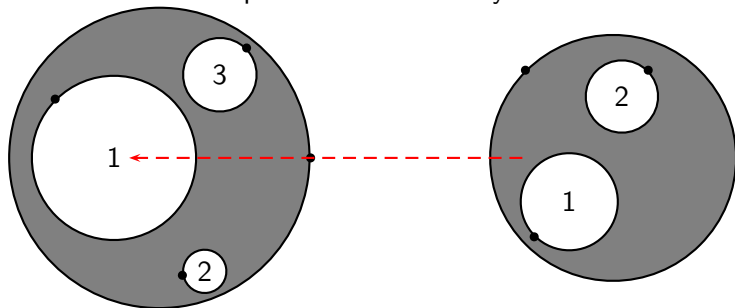
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

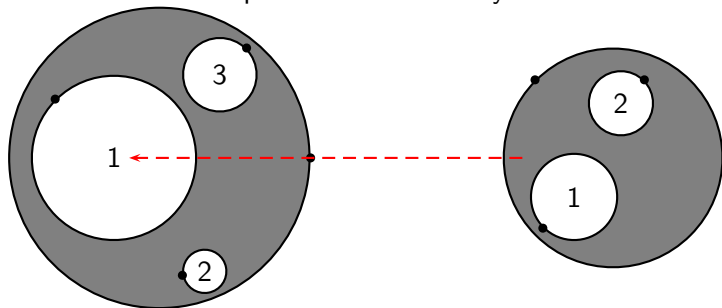
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

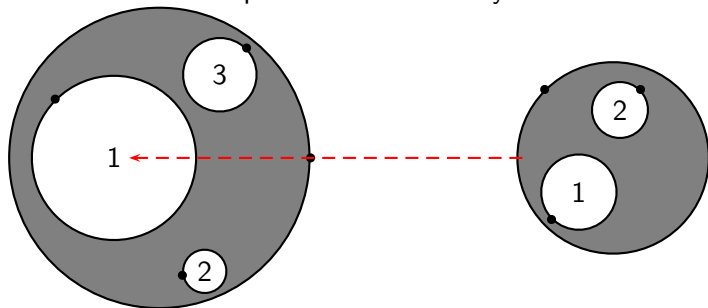
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

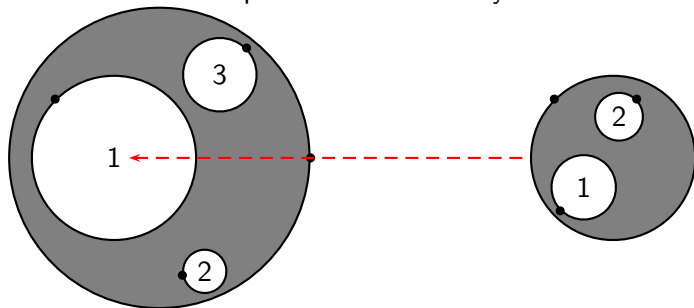
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

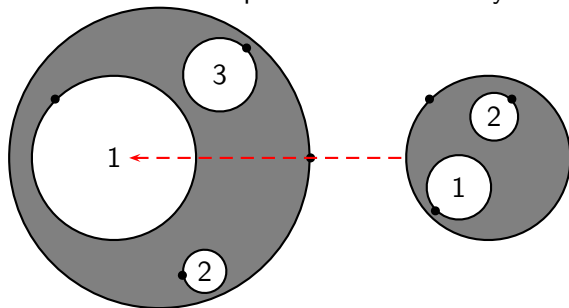
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

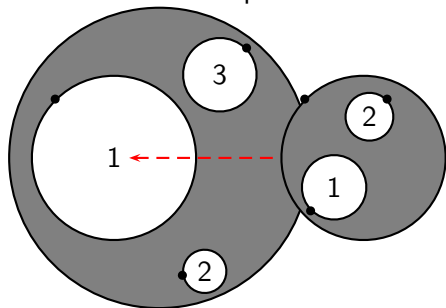
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.

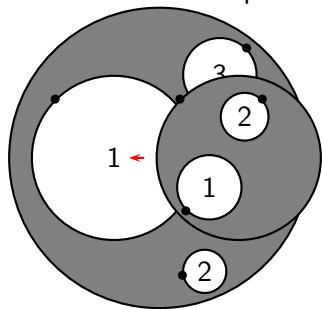


We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.



## The framed little disks

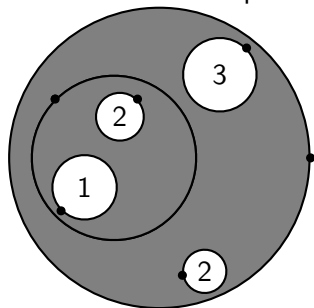
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

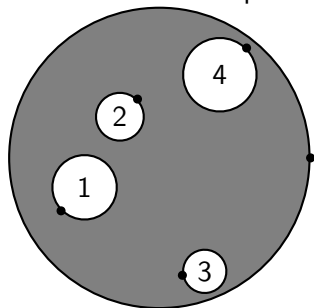
Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

## The framed little disks

Consider the space made up of  $n$  disjoint disks in the standard disk, each one with a marked point on its boundary.



We can compose two configurations by shrinking one down and gluing it in, rotating to match marked points and relabeling.

# Actions of the framed little disks

The framed little disks acts on  $W$  if:

## Actions of the framed little disks

The framed little disks acts on  $W$  if:

- there is an operation  $W^n \rightarrow W$  for each point in  $FLD(n)$

## Actions of the framed little disks

The framed little disks acts on  $W$  if:

- there is an operation  $W^n \rightarrow W$  for each point in  $FLD(n)$
- these operations vary continuously, and

## Actions of the framed little disks

The framed little disks acts on  $W$  if:

- there is an operation  $W^n \rightarrow W$  for each point in  $FLD(n)$
- these operations vary continuously, and
- their composition behaves well with respect to the composition of framed little disks.

## Actions of the framed little disks

The framed little disks acts on  $W$  if:

- there is an operation  $W^n \rightarrow W$  for each point in  $FLD(n)$
- these operations vary continuously, and
- their composition behaves well with respect to the composition of framed little disks.

### Example

$$W = \Omega^2 X = \text{Hom}((D^2; S^1); (X, *))$$



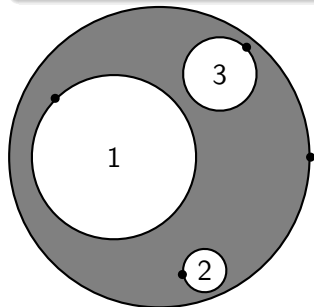
## Actions of the framed little disks

The framed little disks acts on  $W$  if:

- there is an operation  $W^n \rightarrow W$  for each point in  $FLD(n)$
- these operations vary continuously, and
- their composition behaves well with respect to the composition of framed little disks.

### Example

$$W = \Omega^2 X = \text{Hom}((D^2; S^1); (X, *))$$



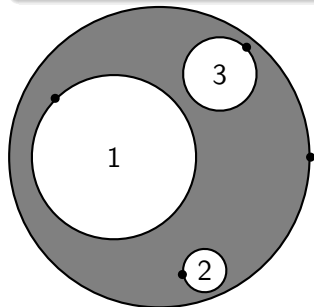
## Actions of the framed little disks

The framed little disks acts on  $W$  if:

- there is an operation  $W^n \rightarrow W$  for each point in  $FLD(n)$
- these operations vary continuously, and
- their composition behaves well with respect to the composition of framed little disks.

### Example

$$W = \Omega^2 X = \text{Hom}((D^2; S^1); (X, *))$$



$(f, g, h)$

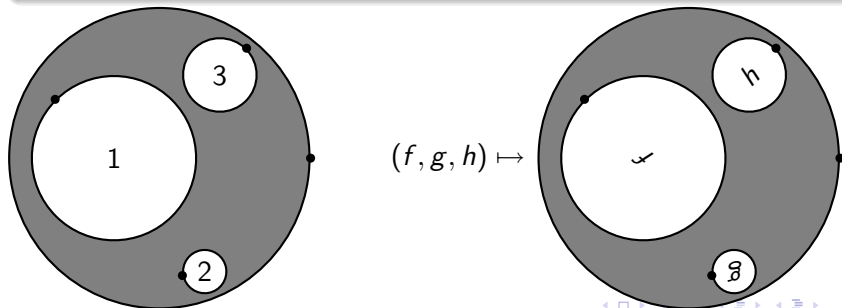
## Actions of the framed little disks

The framed little disks acts on  $W$  if:

- there is an operation  $W^n \rightarrow W$  for each point in  $FLD(n)$
- these operations vary continuously, and
- their composition behaves well with respect to the composition of framed little disks.

### Example

$$W = \Omega^2 X = \text{Hom}((D^2; S^1); (X, *))$$

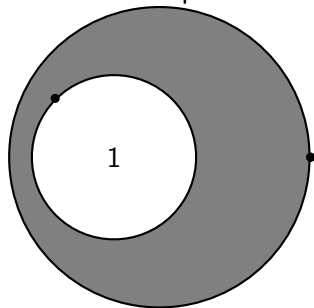


# $S^1$ in the framed little disks

Consider the space of one framed little disk.

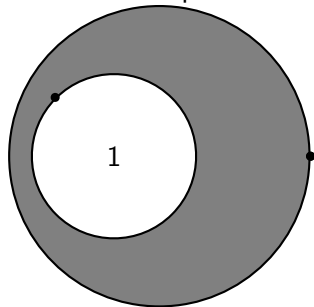
# $S^1$ in the framed little disks

Consider the space of one framed little disk.



# $S^1$ in the framed little disks

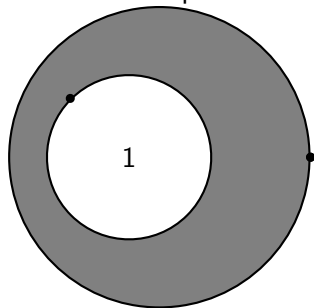
Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin

# $S^1$ in the framed little disks

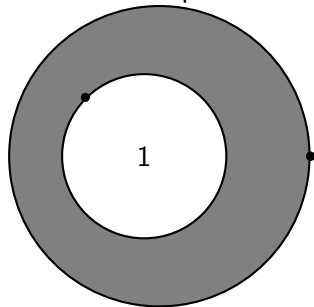
Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin

# $S^1$ in the framed little disks

Consider the space of one framed little disk.

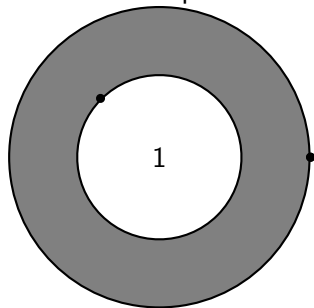


We can deformation retract the center of the disk to the origin



# $S^1$ in the framed little disks

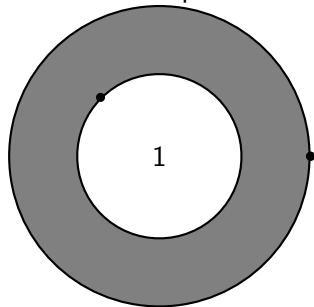
Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin

# $S^1$ in the framed little disks

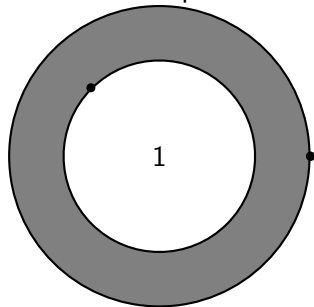
Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin and then the radius of the disk to 1,

# $S^1$ in the framed little disks

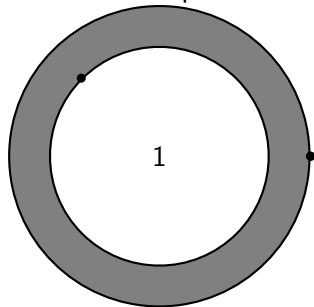
Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin and then the radius of the disk to 1,

# $S^1$ in the framed little disks

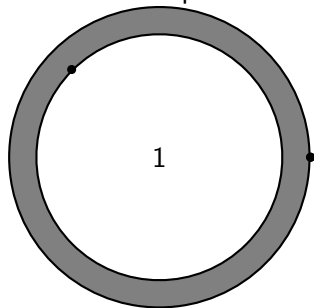
Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin and then the radius of the disk to 1,

# $S^1$ in the framed little disks

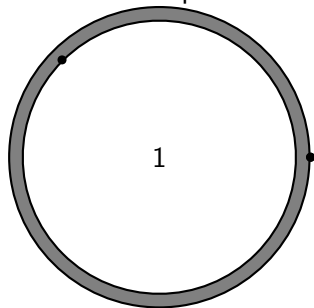
Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin and then the radius of the disk to 1,

# $S^1$ in the framed little disks

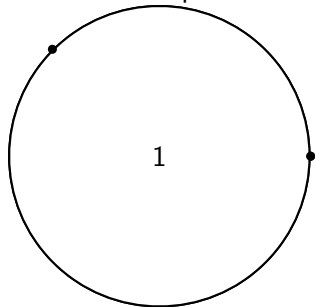
Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin and then the radius of the disk to 1,

# $S^1$ in the framed little disks

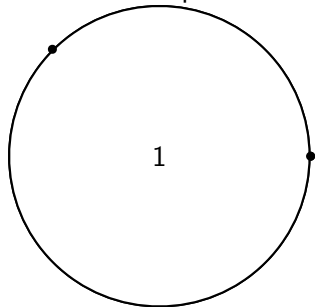
Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin and then the radius of the disk to 1,

# $S^1$ in the framed little disks

Consider the space of one framed little disk.



We can deformation retract the center of the disk to the origin and then the radius of the disk to 1, so this space is homotopy equivalent to  $S^1$ .



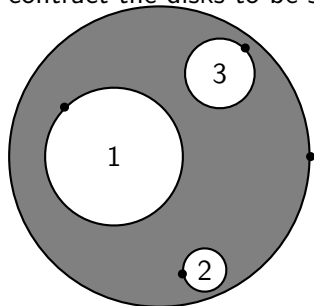
# Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

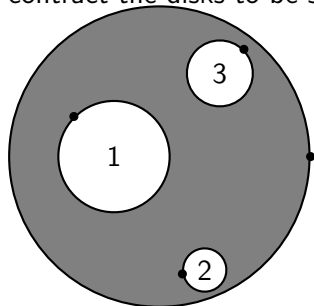
In fact, the space of operations in such a case is contractible. We can contract the disks to be small:



## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

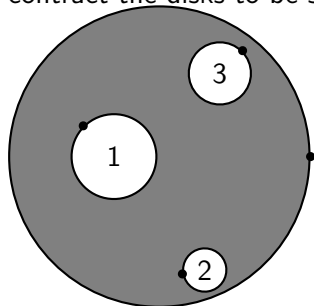
In fact, the space of operations in such a case is contractible. We can contract the disks to be small:



## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

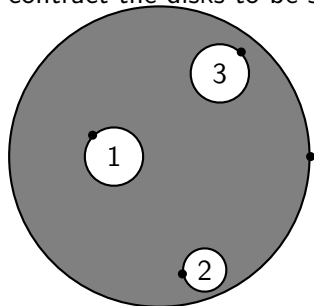
In fact, the space of operations in such a case is contractible. We can contract the disks to be small:



## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

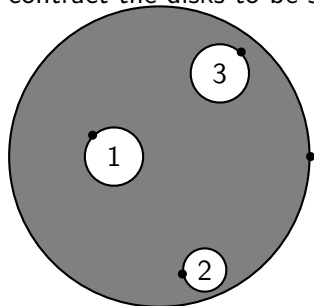
In fact, the space of operations in such a case is contractible. We can contract the disks to be small:



## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

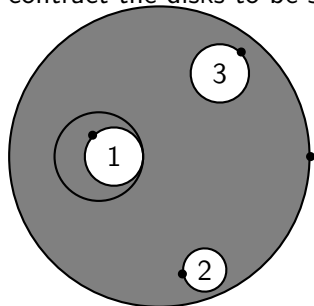


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

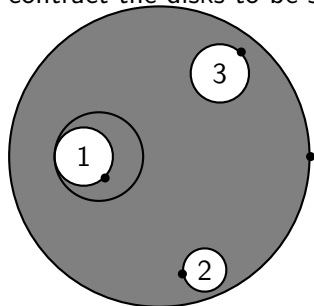


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:



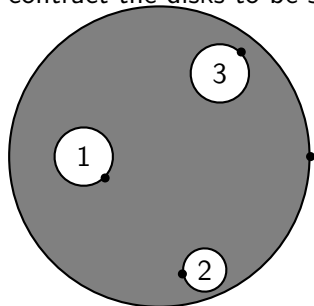
Then configurations of small enough disks can be put in standard position by circle actions.



## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

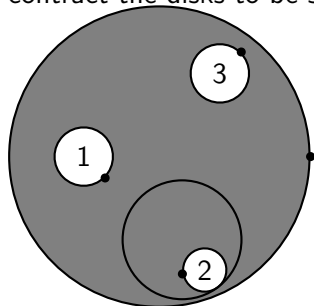


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

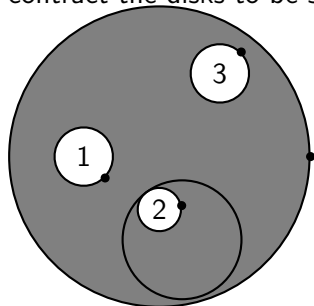


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

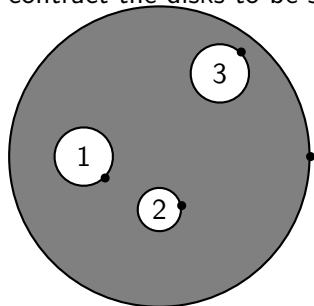


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

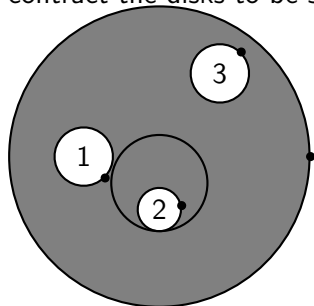


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

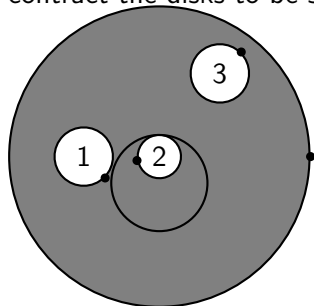


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

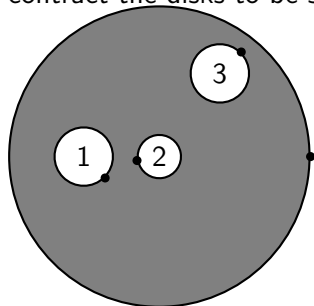


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

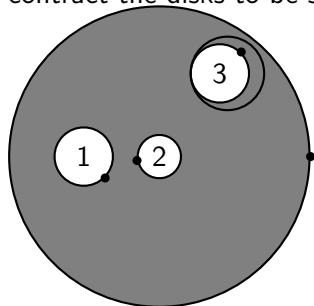


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:



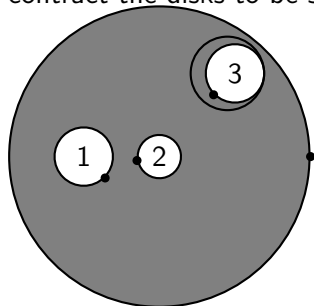
Then configurations of small enough disks can be put in standard position by circle actions.



## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

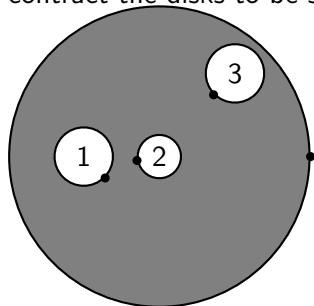


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

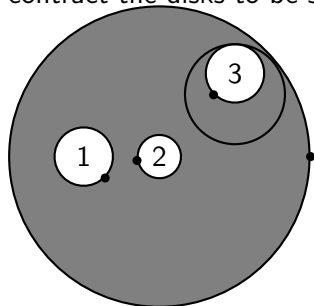


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

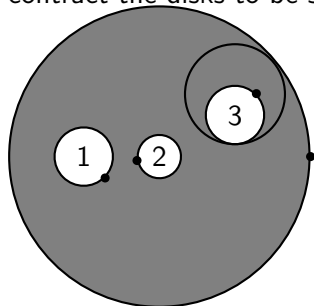


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

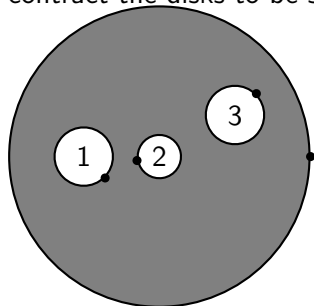


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

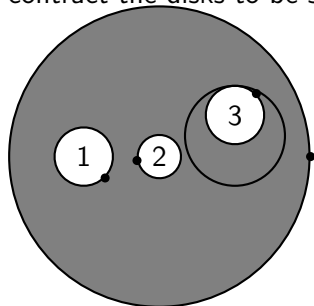


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

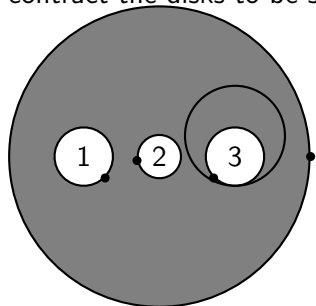


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:

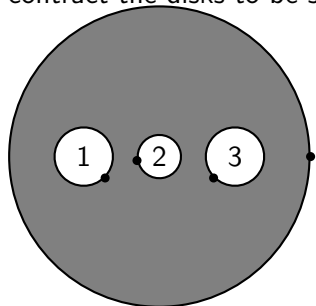


Then configurations of small enough disks can be put in standard position by circle actions.

## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:



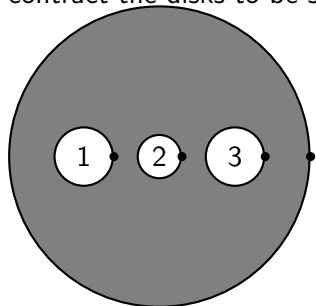
Then configurations of small enough disks can be put in standard position by circle actions.



## Trivializing the circle

What happens if a space is acted on by the framed little disks but the circle acts trivially? In such a case, how does this change the space of operations?

In fact, the space of operations in such a case is contractible. We can contract the disks to be small:



Then configurations of small enough disks can be put in standard position by circle actions.

# Problems with the naive trivialization

This answer is homotopically inadequate.

## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

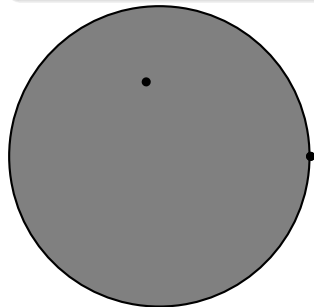
Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.

## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.

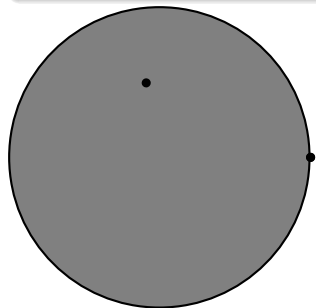


## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.



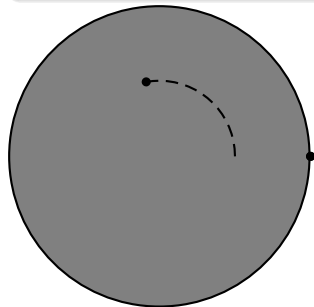
The naive trivialization gives the interval.

## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.



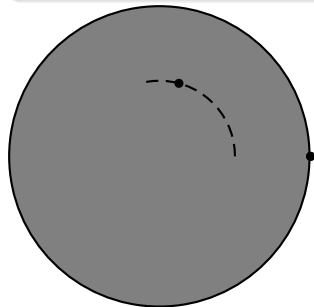
The naive trivialization gives the interval.

## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.



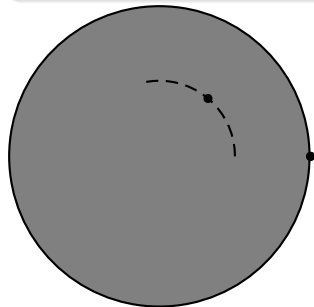
The naive trivialization gives the interval.

## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.



The naive trivialization gives the interval.

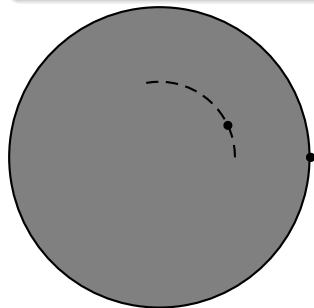


## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.



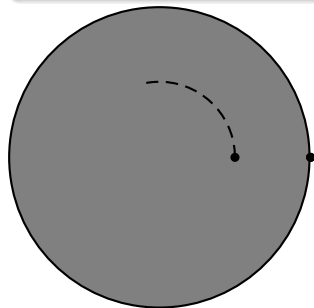
The naive trivialization gives the interval.

## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.



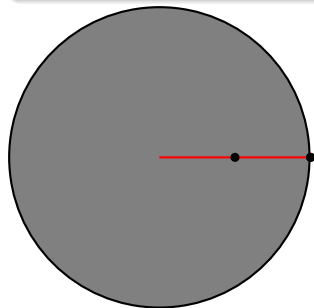
The naive trivialization gives the interval.

## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.



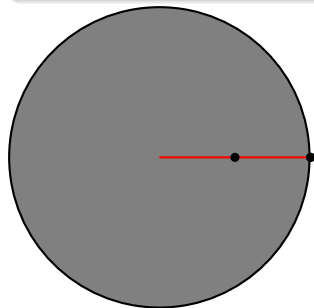
The naive trivialization gives the interval.

## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.



The naive trivialization gives the interval.

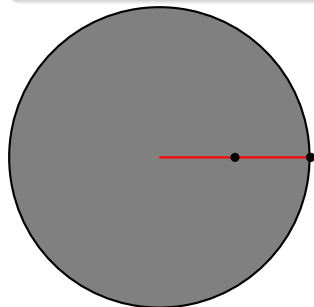
Homotopy equivalent space of operations:  $D^2 \times ES^1$

## Problems with the naive trivialization

This answer is homotopically inadequate.

### Example

Space of operations: the disk  $D^2$ , with the standard multiplication in  $\mathbb{C}$  and the standard circle action.



The naive trivialization gives the interval.

Homotopy equivalent space of operations:  $D^2 \times ES^1$

Naive trivialization:  $BS^1$

# Homotopy trivialization

Moral: To get homotopy invariant information, we need to be more careful.

# Homotopy trivialization

Moral: To get homotopy invariant information, we need to be more careful.

Conjecture/Theorem (Kontsevich, 2005)

# Homotopy trivialization

Moral: To get homotopy invariant information, we need to be more careful.

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of the circle action should be homotopically the same as



# Homotopy trivialization

Moral: To get homotopy invariant information, we need to be more careful.

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of the circle action should be homotopically the same as an action of the genus zero Deligne-Mumford-Knudsen spaces  $\overline{\mathcal{M}}_{0,n}$

# Description of $\mathcal{M}_{0,n}$

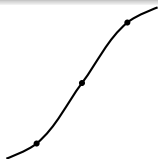
## Definition

$\mathcal{M}_{0,n}$  is the moduli space of configurations of  $n > 2$  points on a genus zero surface up to conformal equivalence

# Description of $\mathcal{M}_{0,n}$

## Definition

$\mathcal{M}_{0,n}$  is the moduli space of configurations of  $n > 2$  points on a genus zero surface up to conformal equivalence

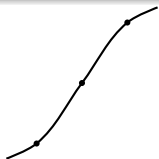


Algebro-geometric

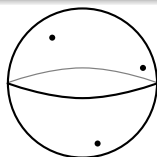
# Description of $\mathcal{M}_{0,n}$

## Definition

$\mathcal{M}_{0,n}$  is the moduli space of configurations of  $n > 2$  points on a genus zero surface up to conformal equivalence



Algebra-geometric

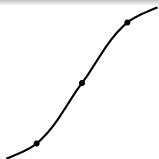


Spherical

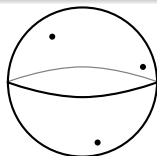
# Description of $\mathcal{M}_{0,n}$

## Definition

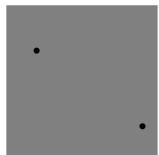
$\mathcal{M}_{0,n}$  is the moduli space of configurations of  $n > 2$  points on a genus zero surface up to conformal equivalence



Albero-geometric



Spherical

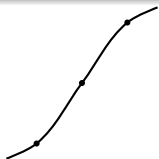


Flat (one point at  $\infty$ )

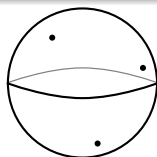
# Description of $\mathcal{M}_{0,n}$

## Definition

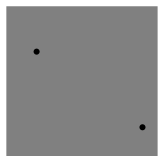
$\mathcal{M}_{0,n}$  is the moduli space of configurations of  $n > 2$  points on a genus zero surface up to conformal equivalence



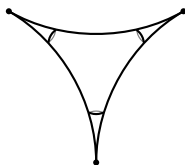
Albro-geometric



Spherical

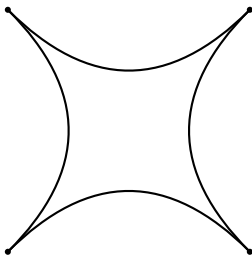


Flat (one point at  $\infty$ )

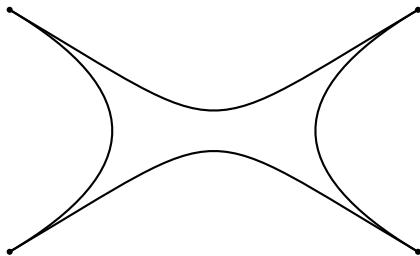


Hyperbolic

# Approaching the boundary of moduli space

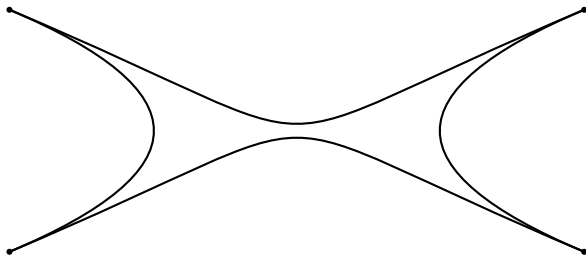


## Approaching the boundary of moduli space

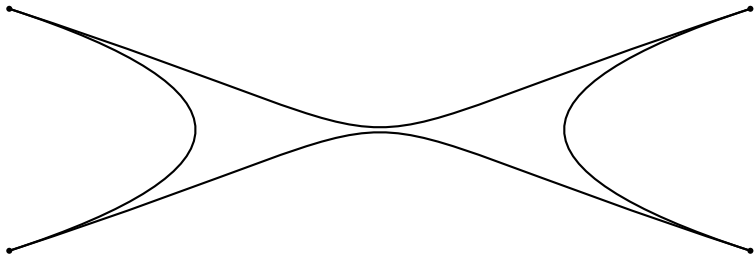




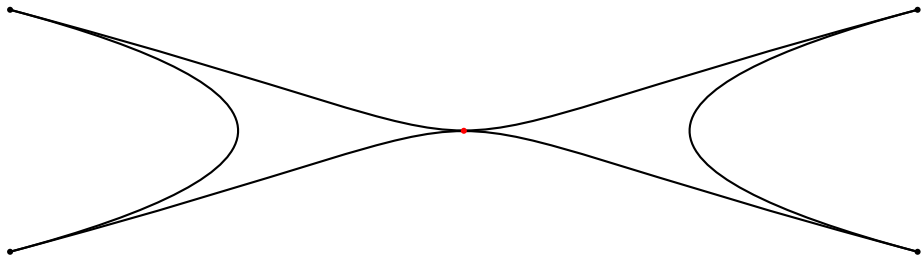
## Approaching the boundary of moduli space



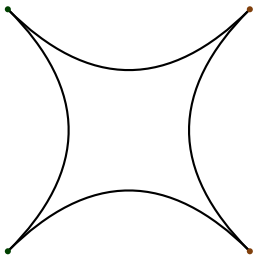
## Approaching the boundary of moduli space



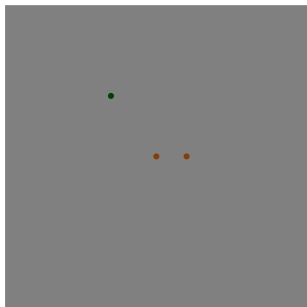
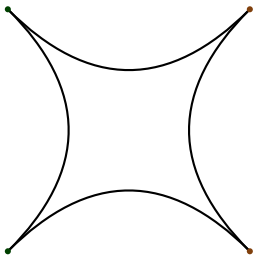
## Approaching the boundary of moduli space



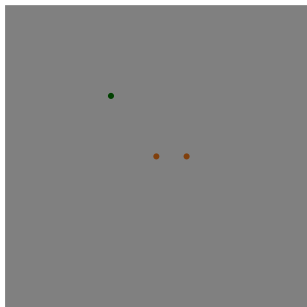
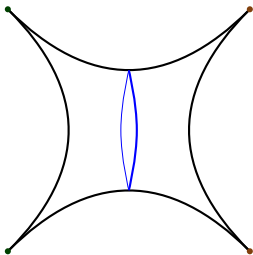
## Approaching the boundary of moduli space



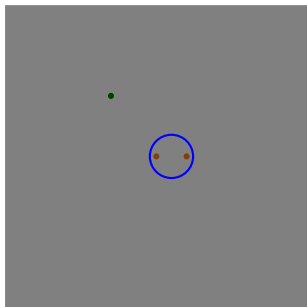
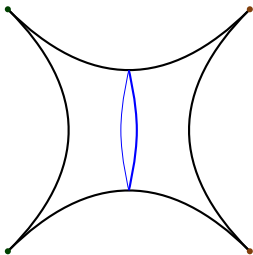
# Approaching the boundary of moduli space



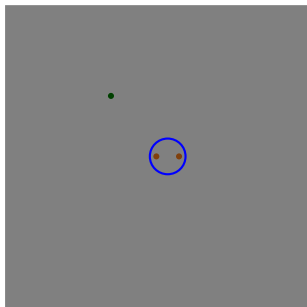
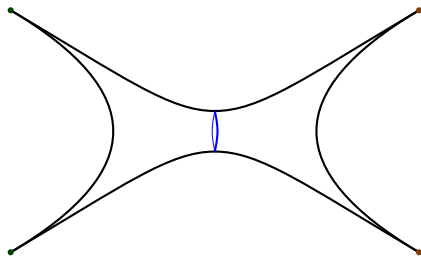
# Approaching the boundary of moduli space



# Approaching the boundary of moduli space

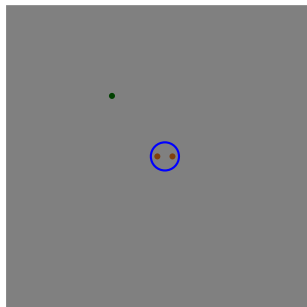
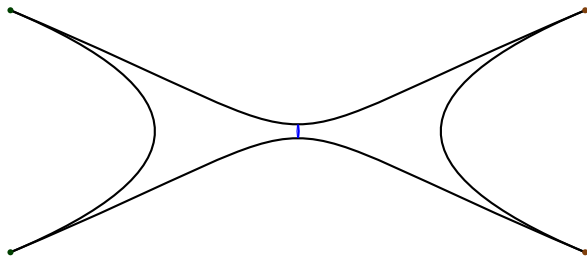


# Approaching the boundary of moduli space

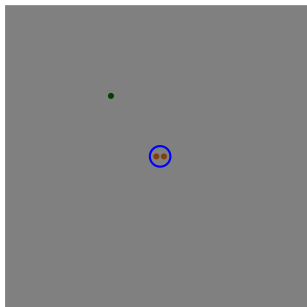
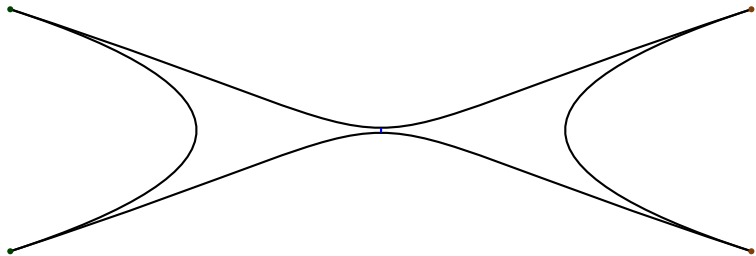




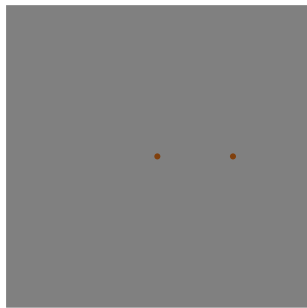
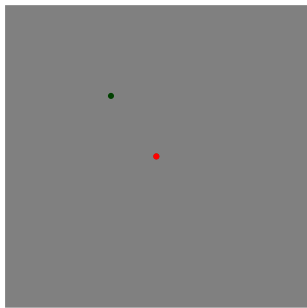
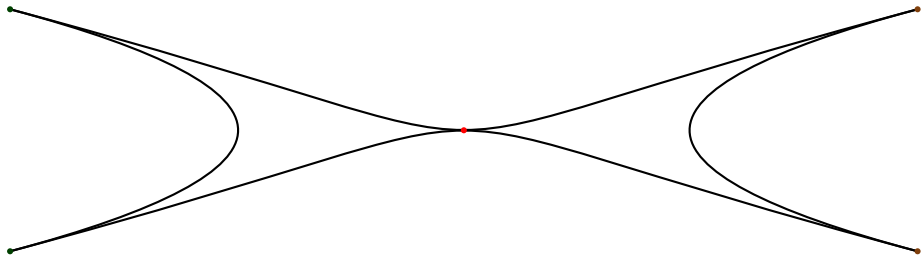
# Approaching the boundary of moduli space



# Approaching the boundary of moduli space



# Approaching the boundary of moduli space



## Sketch of Definition

$\overline{\mathcal{M}}_{0,n+1}$  consists of at least trivalent trees with  $n$  leaves and vertices labeled by  $\mathcal{M}_{0,\text{val}(v)}$ .

## Sketch of Definition

$\overline{\mathcal{M}}_{0,n+1}$  consists of at least trivalent trees with  $n$  leaves and vertices labeled by  $\mathcal{M}_{0,\text{val}(v)}$ .

## Example

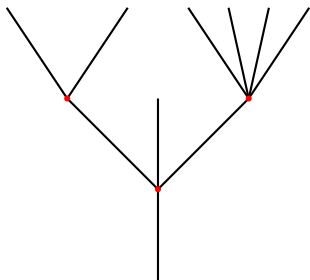
A point in  $\overline{\mathcal{M}}_{0,8}$ :

## Sketch of Definition

$\overline{\mathcal{M}}_{0,n+1}$  consists of at least trivalent trees with  $n$  leaves and vertices labeled by  $\mathcal{M}_{0,\text{val}(v)}$ .

## Example

A point in  $\overline{\mathcal{M}}_{0,8}$ :

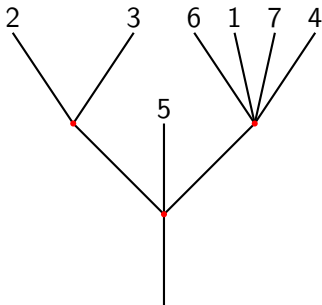


## Sketch of Definition

$\overline{\mathcal{M}}_{0,n+1}$  consists of at least trivalent trees with  $n$  leaves and vertices labeled by  $\mathcal{M}_{0,\text{val}(v)}$ .

## Example

A point in  $\overline{\mathcal{M}}_{0,8}$ :

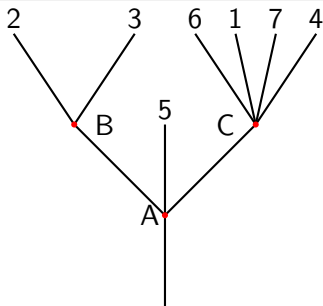


## Sketch of Definition

$\overline{\mathcal{M}}_{0,n+1}$  consists of at least trivalent trees with  $n$  leaves and vertices labeled by  $\mathcal{M}_{0,\text{val}(v)}$ .

## Example

A point in  $\overline{\mathcal{M}}_{0,8}$ :



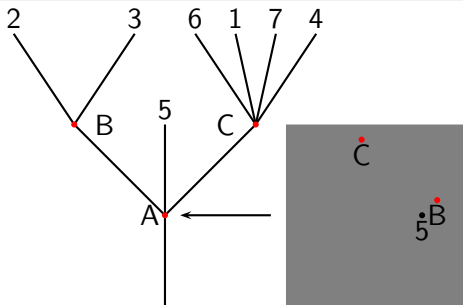


## Sketch of Definition

$\overline{\mathcal{M}}_{0,n+1}$  consists of at least trivalent trees with  $n$  leaves and vertices labeled by  $\mathcal{M}_{0,\text{val}(v)}$ .

## Example

A point in  $\overline{\mathcal{M}}_{0,8}$ :

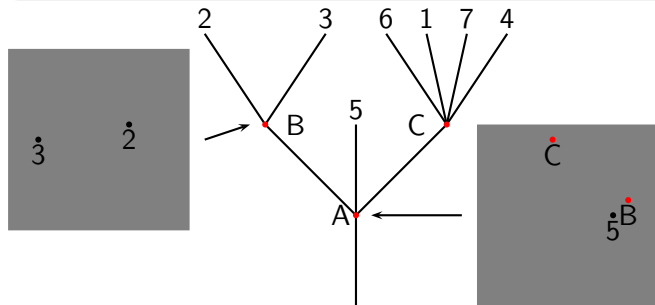


## Sketch of Definition

$\overline{\mathcal{M}}_{0,n+1}$  consists of at least trivalent trees with  $n$  leaves and vertices labeled by  $\mathcal{M}_{0,\text{val}(v)}$ .

## Example

A point in  $\overline{\mathcal{M}}_{0,8}$ :

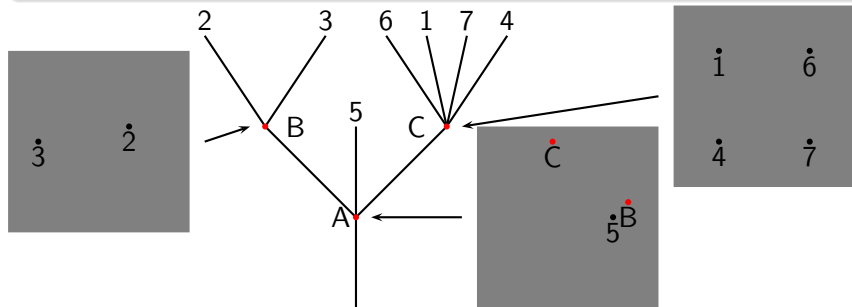


## Sketch of Definition

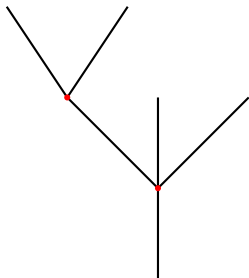
$\overline{\mathcal{M}}_{0,n+1}$  consists of at least trivalent trees with  $n$  leaves and vertices labeled by  $\mathcal{M}_{0,\text{val}(v)}$ .

## Example

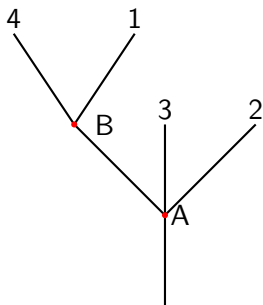
A point in  $\overline{\mathcal{M}}_{0,8}$ :



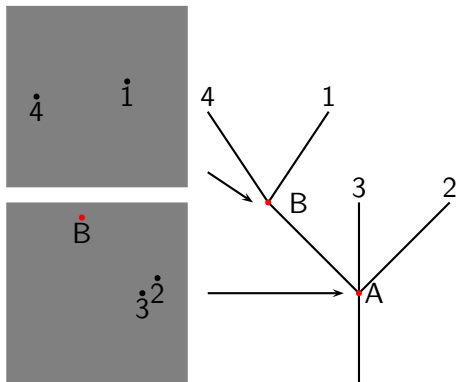
# Composition in $\overline{\mathcal{M}}_{0,n}$



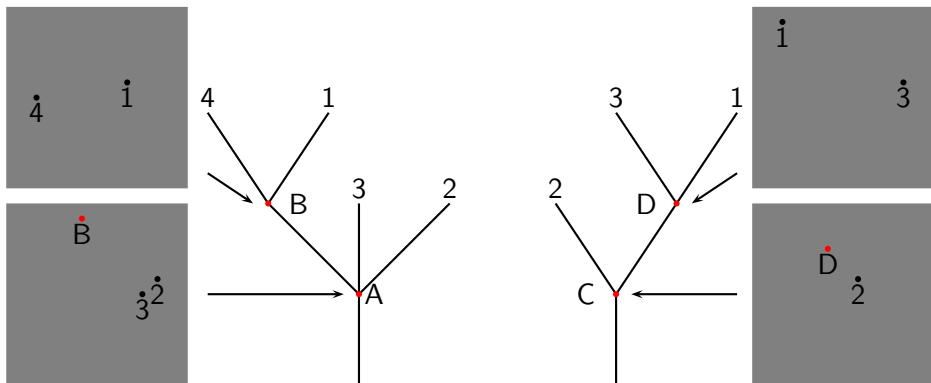
# Composition in $\overline{\mathcal{M}}_{0,n}$



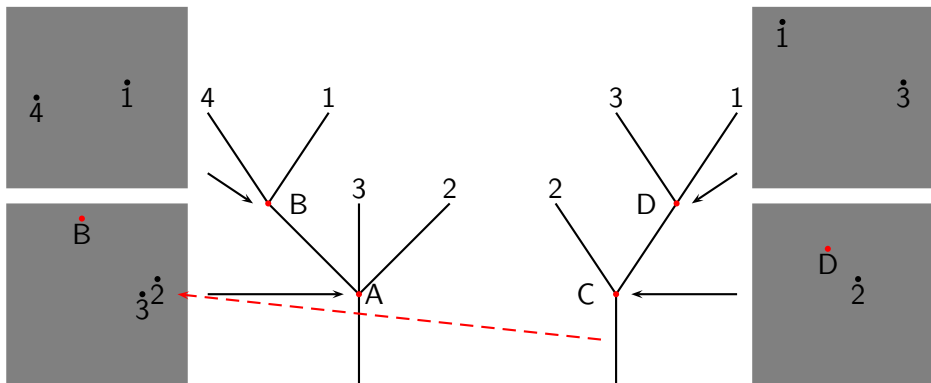
# Composition in $\overline{\mathcal{M}}_{0,n}$



# Composition in $\overline{\mathcal{M}}_{0,n}$

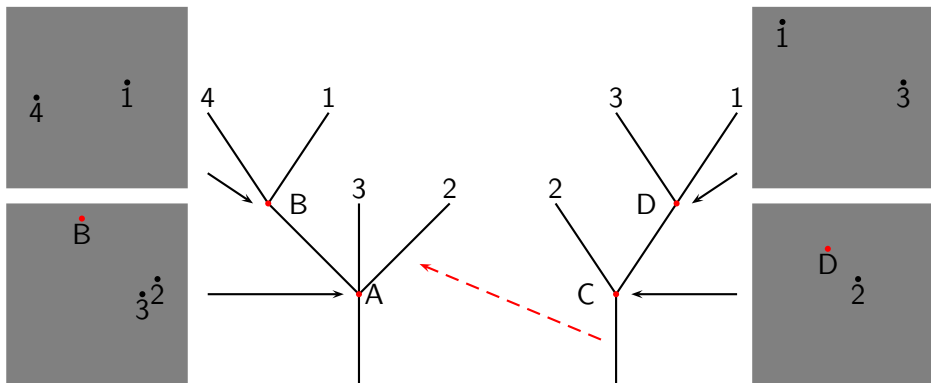


# Composition in $\overline{\mathcal{M}}_{0,n}$

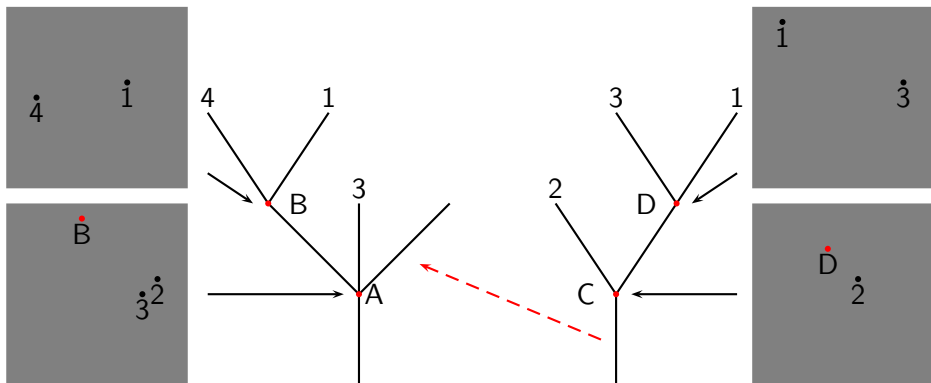




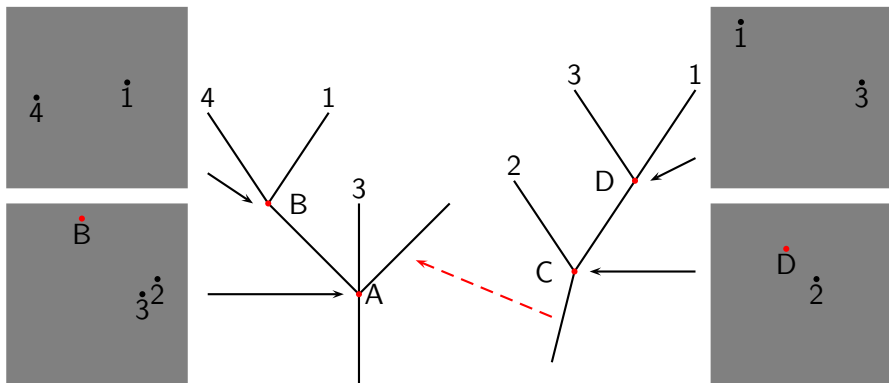
# Composition in $\overline{\mathcal{M}}_{0,n}$



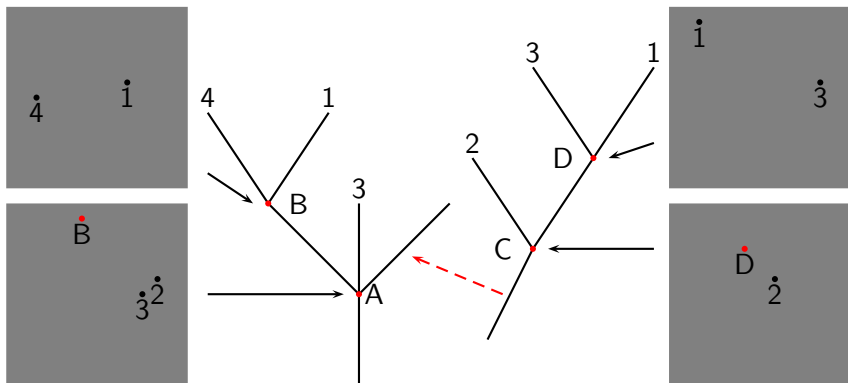
# Composition in $\overline{\mathcal{M}}_{0,n}$



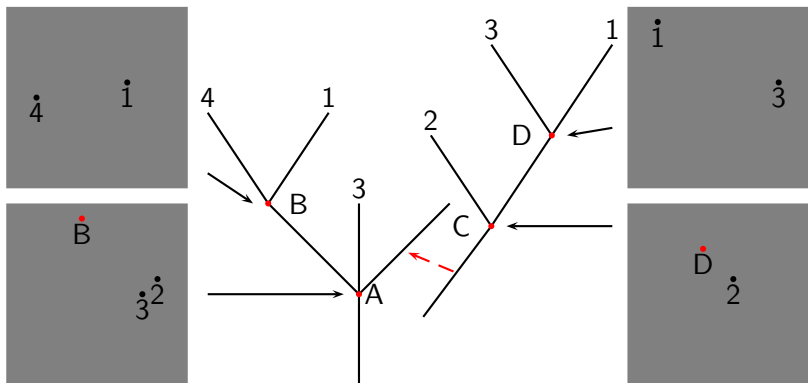
# Composition in $\overline{\mathcal{M}}_{0,n}$



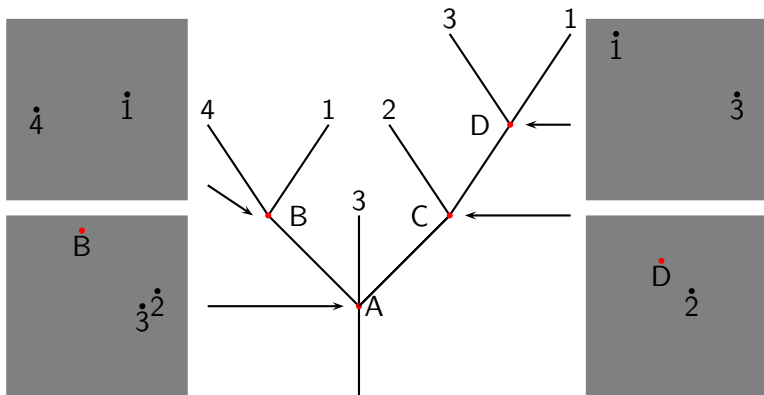
# Composition in $\overline{\mathcal{M}}_{0,n}$



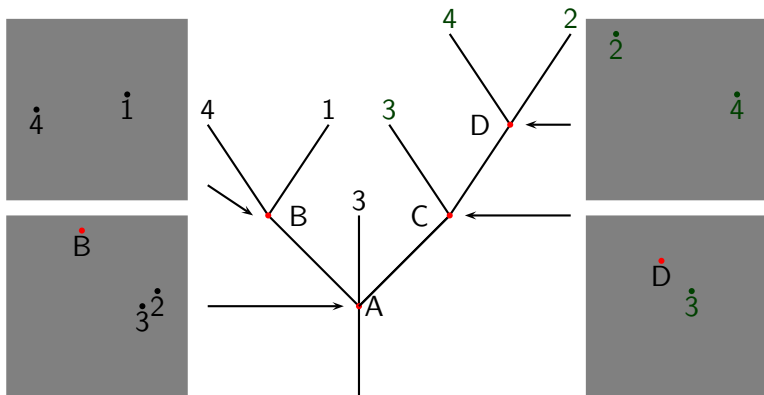
# Composition in $\overline{\mathcal{M}}_{0,n}$



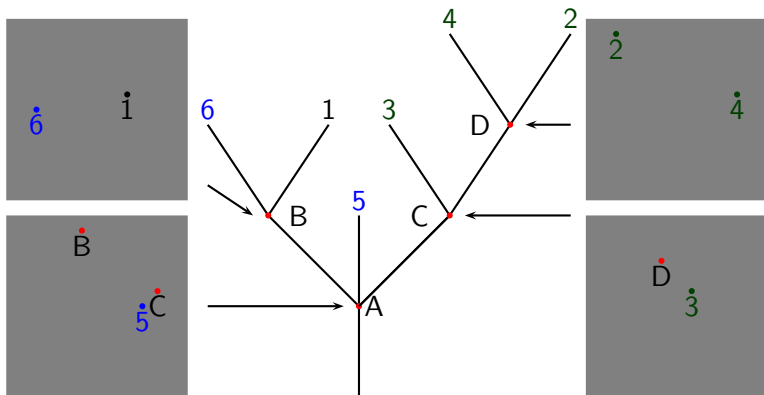
# Composition in $\overline{\mathcal{M}}_{0,n}$



# Composition in $\overline{\mathcal{M}}_{0,n}$



# Composition in $\overline{\mathcal{M}}_{0,n}$





# A framework for Kontsevich's statement

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of  $S^1$  should be homotopically the same as an action of  $\overline{\mathcal{M}}$

# A framework for Kontsevich's statement

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of  $S^1$  should be homotopically the same as an action of  $\overline{\mathcal{M}}$

## Theorem (Kontsevich?; D.-Vallette)

$$\begin{array}{c} S^1 \\ \downarrow \\ FLD \end{array}$$

# A framework for Kontsevich's statement

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of  $S^1$  should be homotopically the same as an action of  $\overline{\mathcal{M}}$

## Theorem (Kontsevich?; D.-Vallette)

$$\begin{array}{c} H_{\mathbb{Q}}(S^1) \\ \downarrow \\ H_{\mathbb{Q}}(FLD) \end{array}$$

# A framework for Kontsevich's statement

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of  $S^1$  should be homotopically the same as an action of  $\overline{\mathcal{M}}$

## Theorem (Kontsevich?; D.-Vallette)

$$\begin{array}{c} H_{\mathbb{Q}}(S^1)_{\infty} \\ \downarrow \\ H_{\mathbb{Q}}(FLD)_{\infty} \end{array}$$

# A framework for Kontsevich's statement

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of  $S^1$  should be homotopically the same as an action of  $\overline{\mathcal{M}}$

## Theorem (Kontsevich?; D.-Vallette)

$$\begin{array}{ccc} H_{\mathbb{Q}}(S^1)_{\infty} & \longrightarrow & \mathbb{Q} \\ \downarrow & & \\ H_{\mathbb{Q}}(FLD)_{\infty} & & \end{array}$$

# A framework for Kontsevich's statement

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of  $S^1$  should be homotopically the same as an action of  $\overline{\mathcal{M}}$

## Theorem (Kontsevich?; D.-Vallette)

*The pushout of:*

$$\begin{array}{ccc} H_{\mathbb{Q}}(S^1)_{\infty} & \longrightarrow & \mathbb{Q} \\ \downarrow & & \\ H_{\mathbb{Q}}(FLD)_{\infty} & & \end{array}$$

is  $H_{\mathbb{Q}}(\overline{\mathcal{M}})_{\infty}$

# A framework for Kontsevich's statement

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of  $S^1$  should be homotopically the same as an action of  $\overline{\mathcal{M}}$

## Theorem (Kontsevich?; D.-Vallette)

*The homotopy pushout of:*

$$\begin{array}{ccc} H_{\mathbb{Q}}(S^1) & \longrightarrow & \mathbb{Q} \\ \downarrow & & \\ H_{\mathbb{Q}}(FLD) & & \end{array}$$

is  $H_{\mathbb{Q}}(\overline{\mathcal{M}})$

# A framework for Kontsevich's statement

## Conjecture/Theorem (Kontsevich, 2005)

An action of the framed little disks and a choice of trivialization of  $S^1$  should be homotopically the same as an action of  $\overline{\mathcal{M}}$

## Theorem (Kontsevich?; D.)

*The homotopy pushout of:*

$$\begin{array}{ccc} S^1 & \longrightarrow & * \\ \downarrow & & \\ FLD & & \end{array}$$

is  $\overline{\mathcal{M}}$



# Outline of Proof of Main Theorem

## Theorem

*The (weak) homotopy pushout of  $FLD \leftarrow S^1 \rightarrow *$  is  $\overline{\mathcal{M}}$ .*

# Outline of Proof of Main Theorem

## Theorem

*The (weak) homotopy pushout of  $FLD \leftarrow S^1 \rightarrow *$  is  $\overline{\mathcal{M}}$ .*

- Show that the pushout  $P_{\mathcal{M}}$  of  $FLD \leftarrow FLD(1) \rightarrow tAn$  contains  $\overline{\mathcal{M}}$  as a deformation retract

# Outline of Proof of Main Theorem

## Theorem

*The (weak) homotopy pushout of  $FLD \leftarrow S^1 \rightarrow *$  is  $\overline{\mathcal{M}}$ .*

- Show that the pushout  $P_{\mathcal{M}}$  of  $FLD \leftarrow FLD(1) \rightarrow tAn$  contains  $\overline{\mathcal{M}}$  as a deformation retract
- Show that the pushout  $P_h$  of  $rFLD \leftarrow S^1 \rightarrow tAn$  is a weak homotopy pushout

# Outline of Proof of Main Theorem

## Theorem

*The (weak) homotopy pushout of  $FLD \leftarrow S^1 \rightarrow *$  is  $\overline{\mathcal{M}}$ .*

- Show that the pushout  $P_{\mathcal{M}}$  of  $FLD \leftarrow FLD(1) \rightarrow tAn$  contains  $\overline{\mathcal{M}}$  as a deformation retract
- Show that the pushout  $P_h$  of  $rFLD \leftarrow S^1 \rightarrow tAn$  is a weak homotopy pushout
- Show that the map from the second pushout to the first pushout is a weak homotopy equivalence of operads

# Pushouts of operads

## Reminder

The pushout in groups is the amalgamated product  $A *_B C$ .

# Pushouts of operads

## Reminder

The pushout in groups is the amalgamated product  $A *_B C$ .

A generic element looks like  $ac \dots$ , which we will write like this:

# Pushouts of operads

## Reminder

The pushout in groups is the amalgamated product  $A *_B C$ .

A generic element looks like  $ac \dots$ , which we will write like this:



# Pushouts of operads

## Reminder

The pushout in groups is the amalgamated product  $A *_B C$ .

A generic element looks like  $ac \dots$ , which we will write like this:



$c$



$b$   
 $a$

There are relations coming from  $B$ :

$(ab)c$



# Pushouts of operads

## Reminder

The pushout in groups is the amalgamated product  $A *_B C$ .

A generic element looks like  $ac \dots$ , which we will write like this:



There are relations coming from  $B$ :

$$(ab)c = abc$$

# Pushouts of operads

## Reminder

The pushout in groups is the amalgamated product  $A *_B C$ .

A generic element looks like  $ac \dots$ , which we will write like this:



There are relations coming from  $B$ :

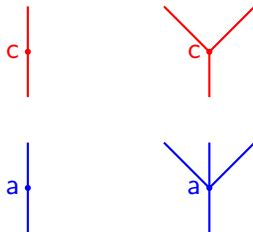
$$(ab)c = abc = a(bc)$$

# Pushouts of operads

## Fact

The pushout in operads is the amalgamated product  $A *_B C$ .

A generic element looks like  $ac \cdots$ , which we will write like this:

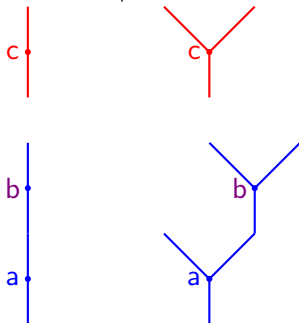


# Pushouts of operads

## Fact

The pushout in operads is the amalgamated product  $A *_B C$ .

A generic element looks like  $ac \dots$ , which we will write like this:



There are relations coming from  $B$ :

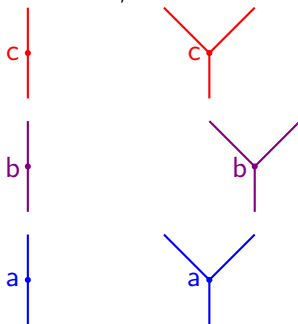
$$(ab)c$$

# Pushouts of operads

## Fact

The pushout in operads is the amalgamated product  $A *_B C$ .

A generic element looks like  $ac \dots$ , which we will write like this:



There are relations coming from  $B$ :

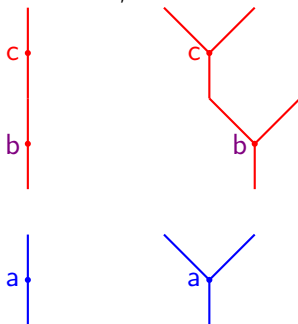
$$(ab)c = abc$$

# Pushouts of operads

## Fact

The pushout in operads is the amalgamated product  $A *_B C$ .

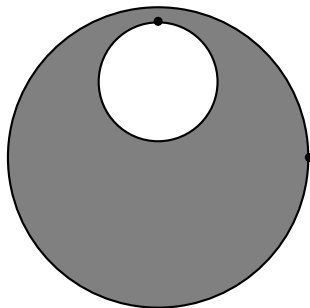
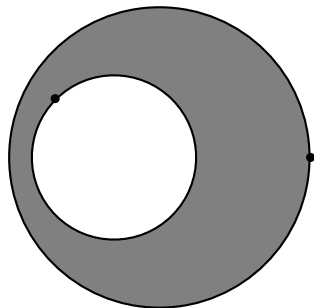
A generic element looks like  $ac \dots$ , which we will write like this:



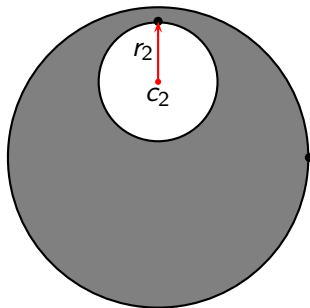
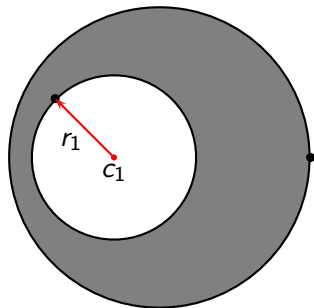
There are relations coming from  $B$ :

$$(ab)c = abc = a(bc)$$

## $FLD(1)$ and the affine group

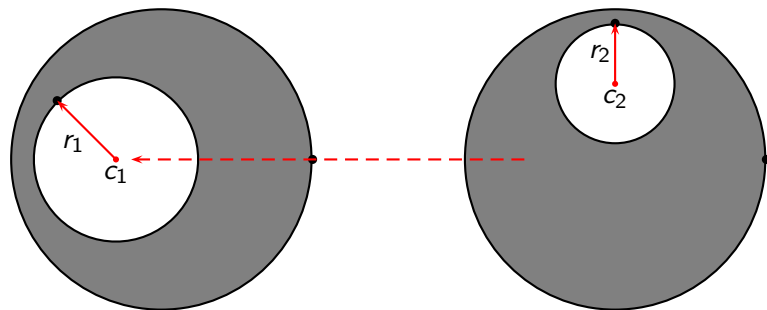


## $FLD(1)$ and the affine group

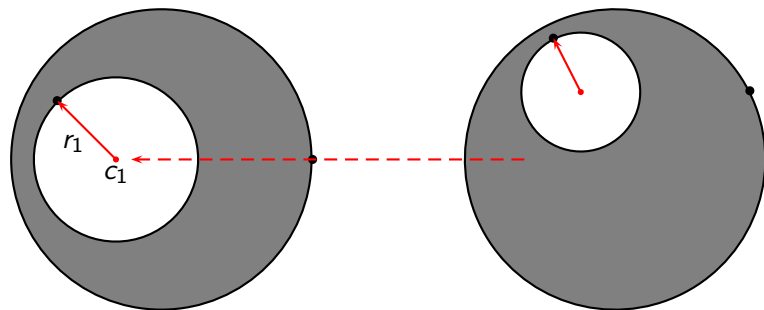




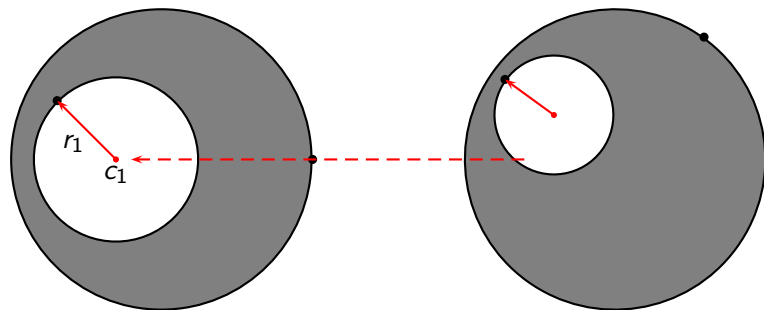
## $FLD(1)$ and the affine group



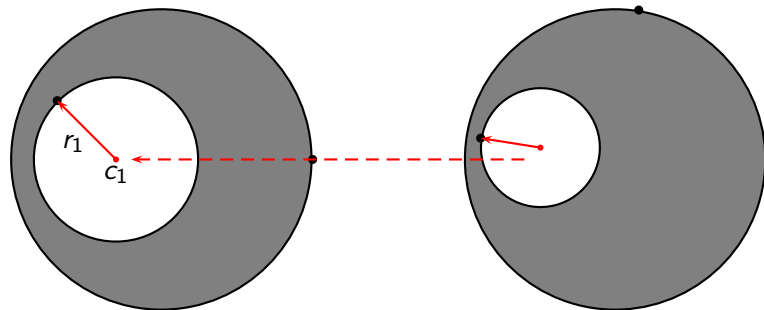
## $FLD(1)$ and the affine group



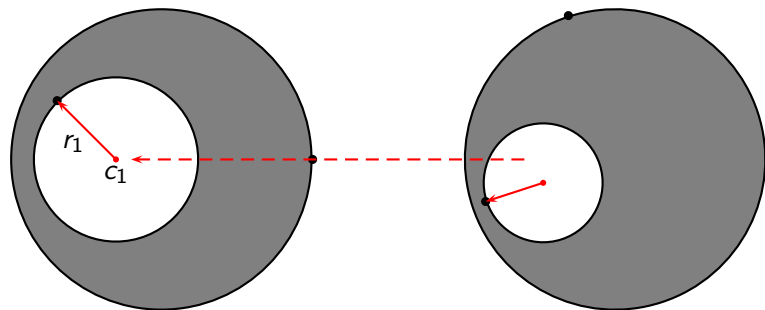
## $FLD(1)$ and the affine group



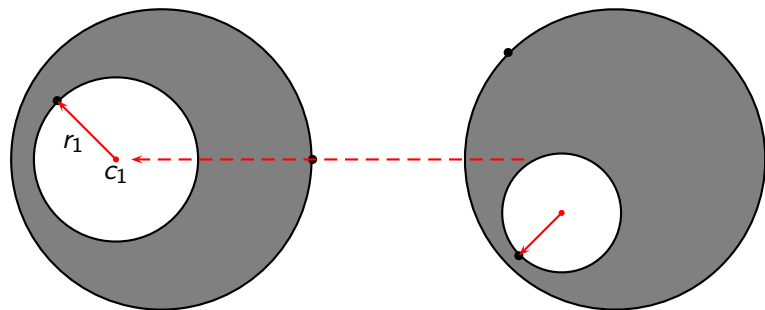
## $FLD(1)$ and the affine group



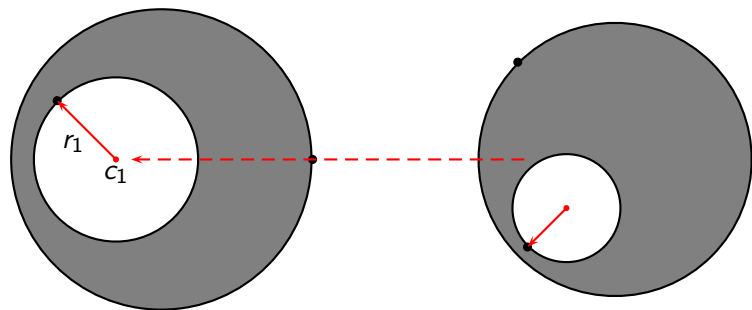
## $FLD(1)$ and the affine group



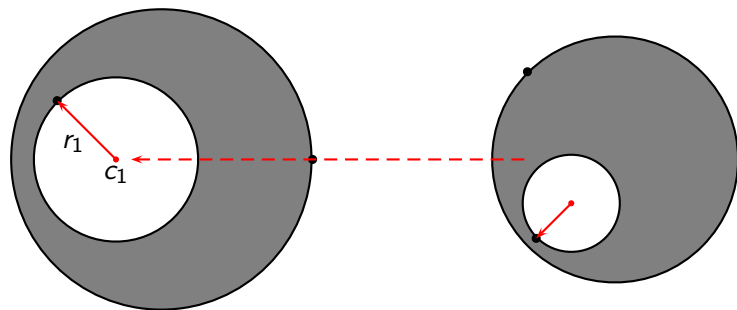
## $FLD(1)$ and the affine group



## $FLD(1)$ and the affine group

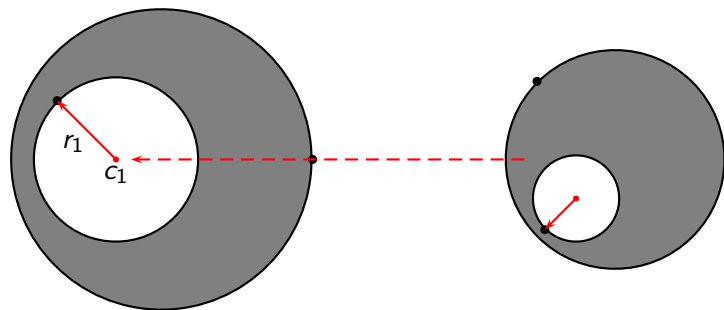


## $FLD(1)$ and the affine group

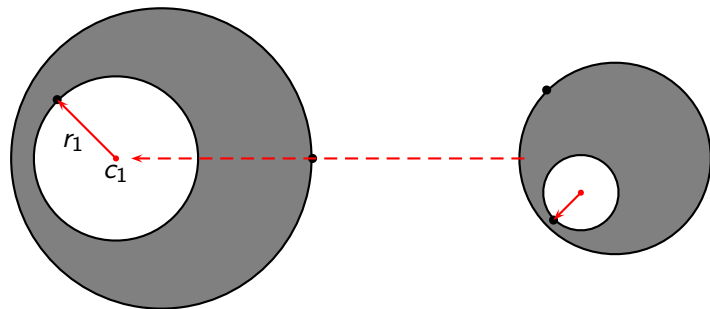




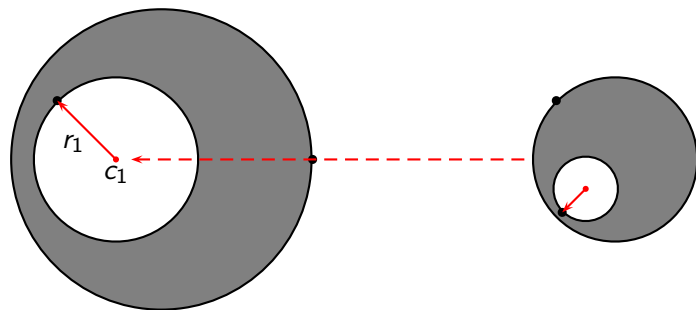
## $FLD(1)$ and the affine group



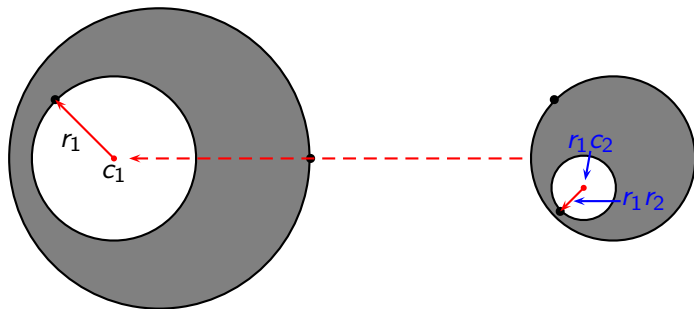
# $FLD(1)$ and the affine group



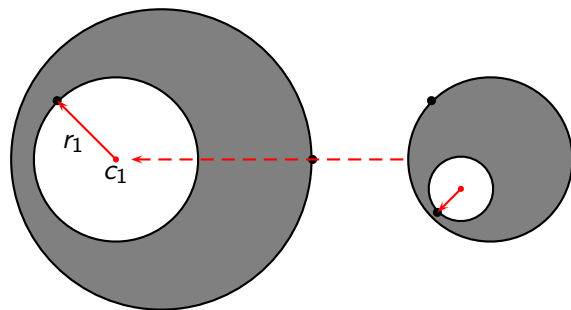
# $FLD(1)$ and the affine group



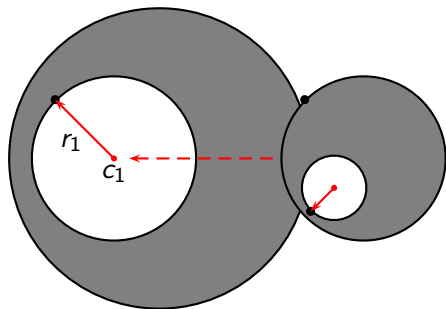
# $FLD(1)$ and the affine group



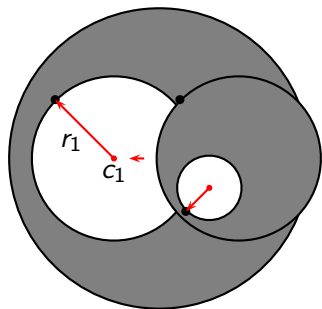
## $FLD(1)$ and the affine group



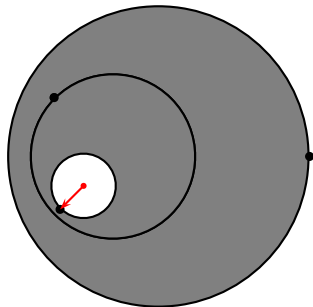
## $FLD(1)$ and the affine group



# $FLD(1)$ and the affine group

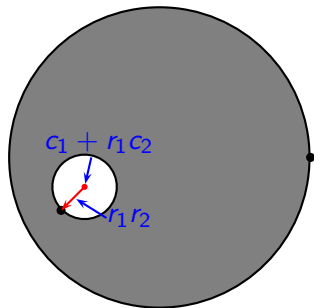


# $FLD(1)$ and the affine group

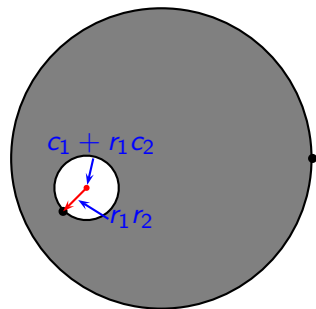




# $FLD(1)$ and the affine group

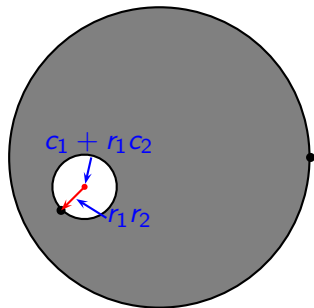


## $FLD(1)$ and the affine group



$$(c_1, r_1) \circ (c_2, r_2) = (c_1 + r_1 c_2, r_1 r_2)$$

## $FLD(1)$ and the affine group



$$(c_1, r_1) \circ (c_2, r_2) = (c_1 + r_1 c_2, r_1 r_2)$$

### Definition

$\text{Aff } \mathbb{C}$ , the affine group of  $\mathbb{C}$ , is  $\mathbb{C} \times \mathbb{C}^*$  with this product.

## $tAn$ and the affine group

$$(c_1, r_1) \circ (c_2, r_2) = (c_1 + r_1 c_2, r_1 r_2)$$

### Definition

$\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}^*$  with this product.

## $tAn$ and the affine group

$$(c_1, r_1) \circ (c_2, r_2) = (c_1 + r_1 c_2, r_1 r_2)$$

### Definition

$\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}^*$  with this product.

### Fact

$FLD(1)$  is the submonoid of  $\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.

## $tAn$ and the affine group

$$(c_1, r_1) \circ (c_2, r_2) = (c_1 + r_1 c_2, r_1 r_2)$$

### Definition

$\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}^*$  with this product.

### Fact

$FLD(1)$  is the submonoid of  $\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.

### Definition

$t\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}$  with this product.

## $tAn$ and the affine group

$$(c_1, r_1) \circ (c_2, r_2) = (c_1 + r_1 c_2, r_1 r_2)$$

### Definition

$\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}^*$  with this product.

### Fact

$FLD(1)$  is the submonoid of  $\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.

### Definition

$t\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}$  with this product.

### Definition

$tAn$  is the submonoid of  $t\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.

## $tAn$ and the affine group

$$(c_1, r_1) \circ (c_2, r_2) = (c_1 + r_1 c_2, r_1 r_2)$$

$$(c_1, r_1) \circ (c_2, 0) = (c_1 + r_1 c_2, 0)$$

### Definition

$\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}^*$  with this product.

### Fact

$FLD(1)$  is the submonoid of  $\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.

### Definition

$t\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}$  with this product.

### Definition

$tAn$  is the submonoid of  $t\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.



## $tAn$ and the affine group

$$(c_1, r_1) \circ (c_2, r_2) = (c_1 + r_1 c_2, r_1 r_2)$$

$$(c_1, r_1) \circ (0, 0) = (c_1, 0)$$

### Definition

$\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}^*$  with this product.

### Fact

$FLD(1)$  is the submonoid of  $\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.

### Definition

$t\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}$  with this product.

### Definition

$tAn$  is the submonoid of  $t\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.

## $tAn$ and the affine group

$$\begin{aligned}(c_1, r_1) \circ (c_2, r_2) &= (c_1 + r_1 c_2, r_1 r_2) \\ (c_1, 0) \circ (c_2, r_2) &= (c_1, 0)\end{aligned}$$

### Definition

$\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}^*$  with this product.

### Fact

$FLD(1)$  is the submonoid of  $\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.

### Definition

$t\text{Aff } \mathbb{C}$  is  $\mathbb{C} \rtimes \mathbb{C}$  with this product.

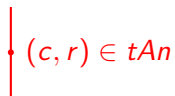
### Definition

$tAn$  is the submonoid of  $t\text{Aff } \mathbb{C}$  with  $|r| + |c| \leq 1$  with this product.

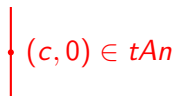
# Describing $P_{\mathcal{M}}$

Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$

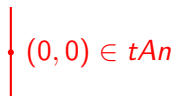
Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



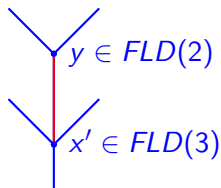
Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$

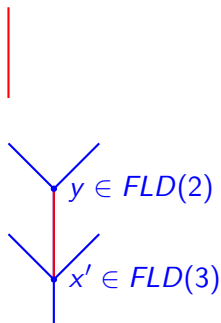


Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$

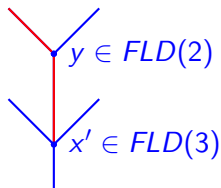




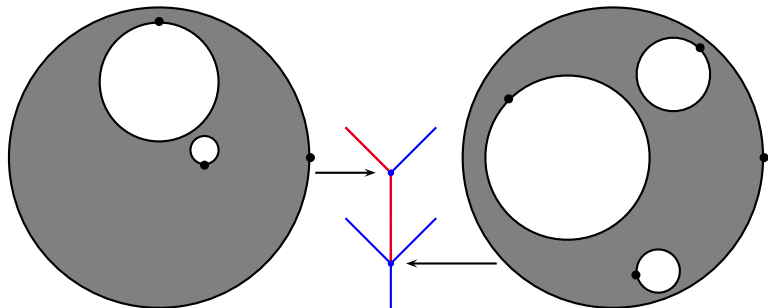
Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



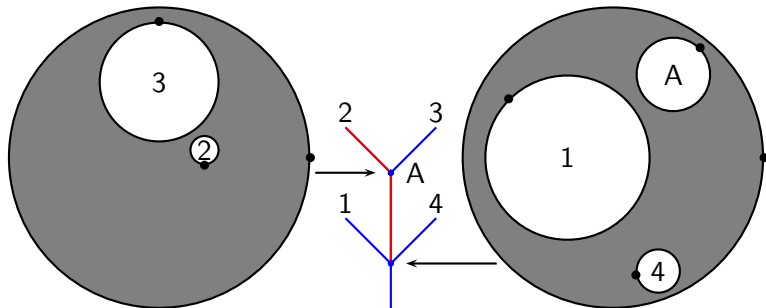
Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



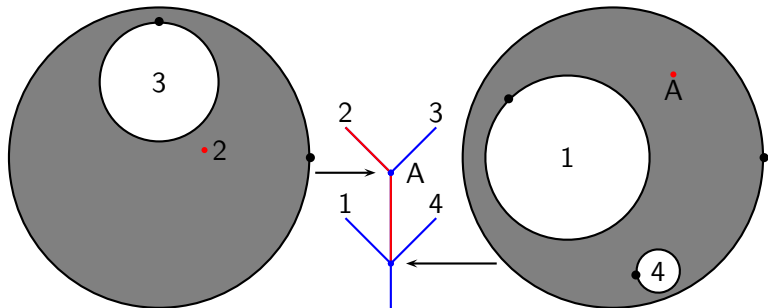
Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



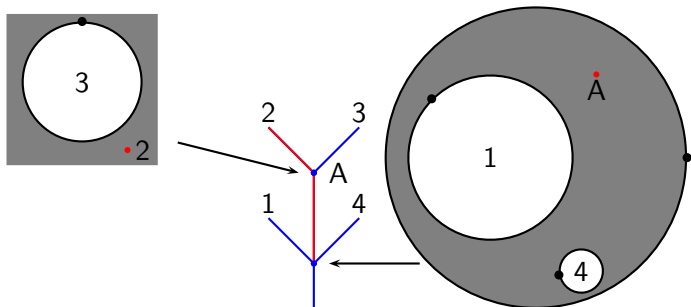
Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



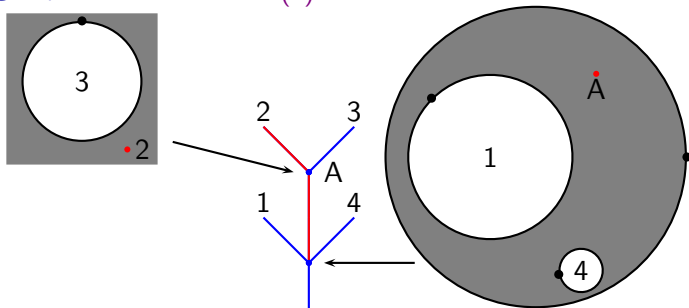
Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



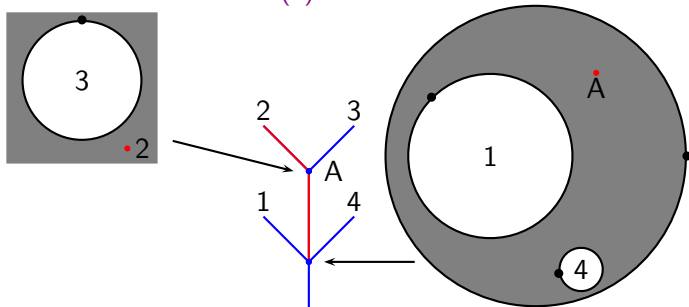
Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$

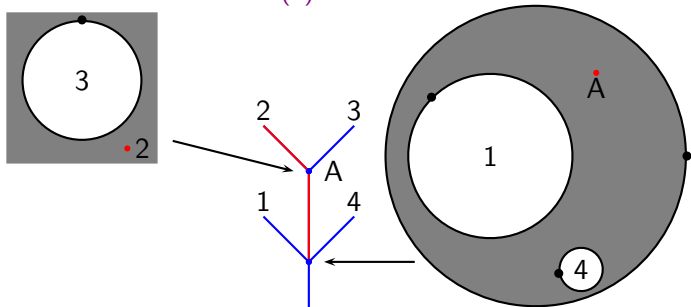


## Description

$P_{\mathcal{M}}$  consists (roughly) of at least trivalent trees with some special (“blue”) external edges and a label on each vertex as follows:



Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$

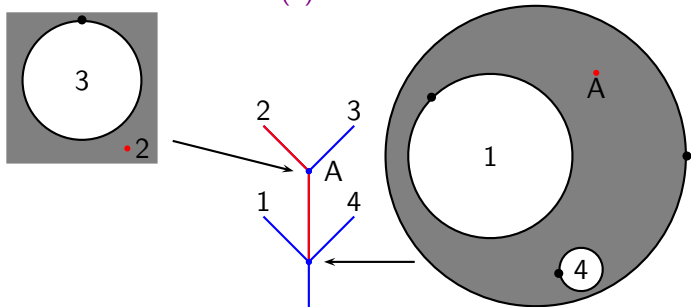


## Description

$P_{\mathcal{M}}$  consists (roughly) of at least trivalent trees with some special (“blue”) external edges and a label on each vertex as follows:

a configuration of **points** and **disks** in the disk (blue outgoing edge)

Describing  $P_{\mathcal{M}} = FLD *_{FLD(1)} tAn$



## Description

$P_{\mathcal{M}}$  consists (roughly) of at least trivalent trees with some special (“blue”) external edges and a label on each vertex as follows:

a configuration of **points** and **disks** in the disk (blue outgoing edge)

a configuration of **points** and **disks** in the plane up to  $\text{Aff } \mathbb{C}$  (red outgoing edge)

## Description

$P_{\mathcal{M}}$  consists of at least trivalent trees with some blue external edges and vertices labeled by:

a configuration of **points** and **disks** in the disk (blue outgoing edge)

a configuration of **points** and **disks** in the plane (red outgoing edge)

up to  $\text{Aff } \mathbb{C}$

## Description

$\mathcal{P}_{\mathcal{M}}$  consists of at least trivalent trees with some blue external edges and vertices labeled by:

a configuration of **points** and **disks** in the disk (blue outgoing edge)

a configuration of **points** and **disks** in the plane (red outgoing edge)

up to  $\text{Aff } \mathbb{C}$

## Reminder

$\overline{\mathcal{M}}$  consists of at least trivalent trees with vertices labeled by:

a configuration of **points** in the plane

up to conformal equivalence

## Description

$P_{\mathcal{M}}$  consists of at least trivalent trees with some blue external edges and vertices labeled by:

a configuration of **points** and **disks** in the disk (blue outgoing edge)

a configuration of **points** and **disks** in the plane (red outgoing edge)

up to  $\text{Aff } \mathbb{C}$

## Reminder

$\overline{\mathcal{M}}$  consists of at least trivalent trees with vertices labeled by:

a configuration of **points** in the plane

up to  $\text{Aff } \mathbb{C}$

## Description

$P_{\mathcal{M}}$  consists of at least trivalent trees with some blue external edges and vertices labeled by:

a configuration of **points** and **disks** in the disk (blue outgoing edge)

a configuration of **points** and **disks** in the plane (red outgoing edge)

up to  $\text{Aff } \mathbb{C}$

## Reminder

$\overline{\mathcal{M}}$  consists of at least trivalent trees with vertices labeled by:

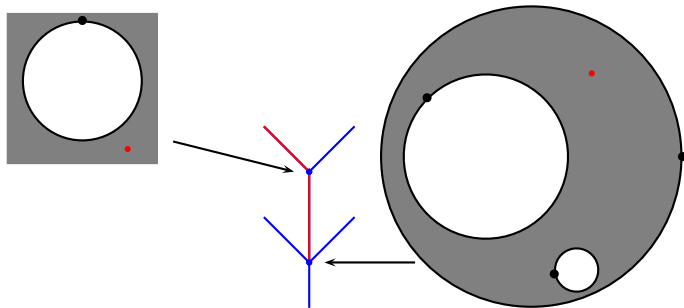
a configuration of **points** in the plane

up to  $\text{Aff } \mathbb{C}$

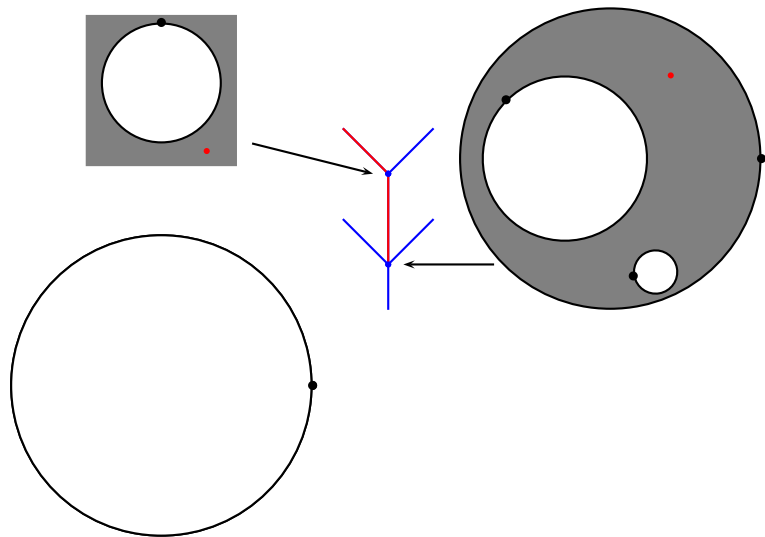
## Goal

Homotope away all blue edges

# Homotoping away the blue edges

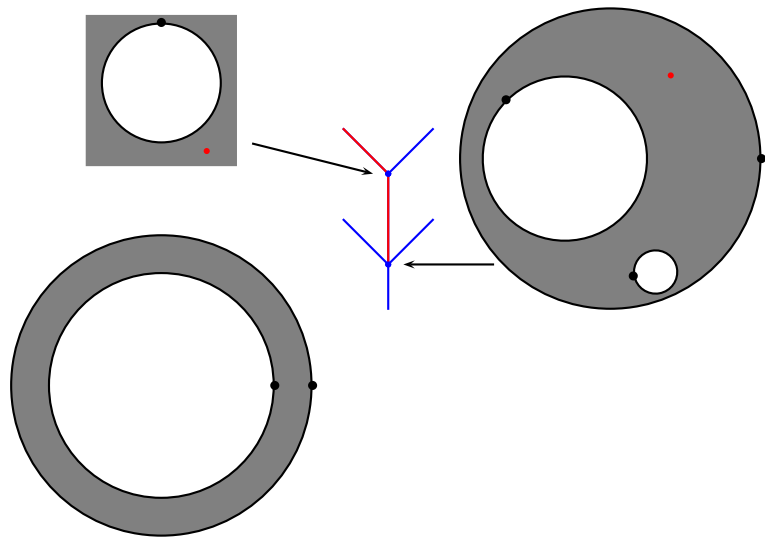


# Homotoping away the blue edges

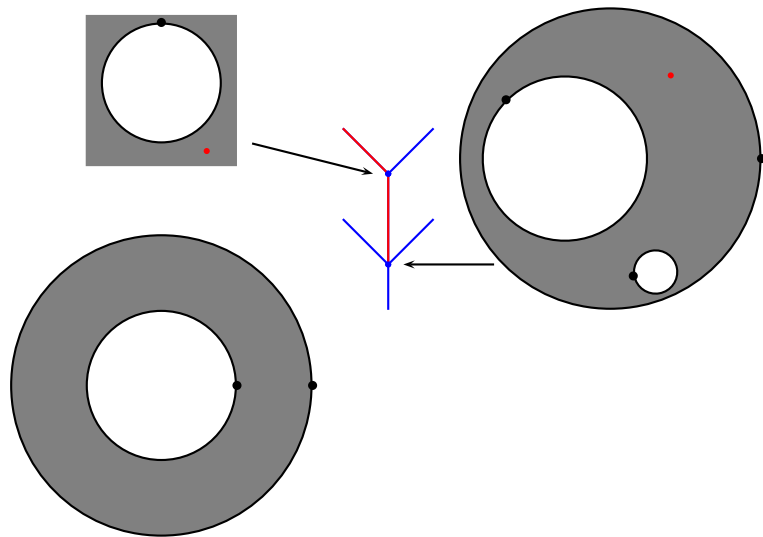




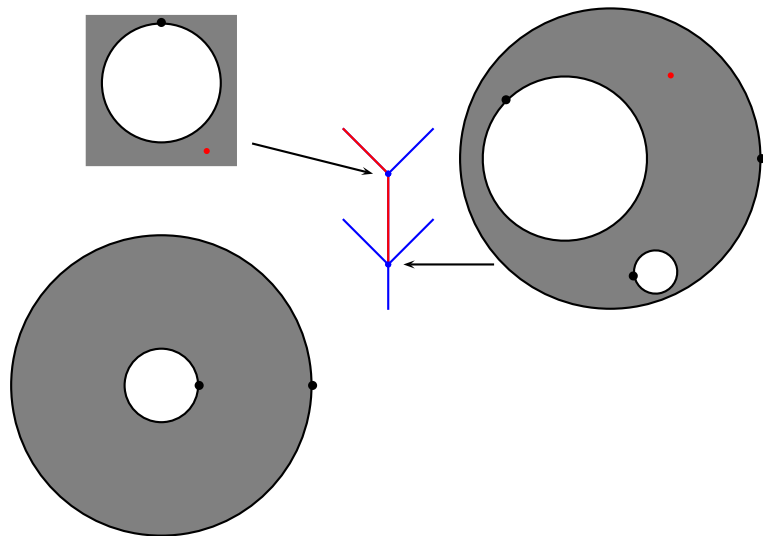
# Homotoping away the blue edges



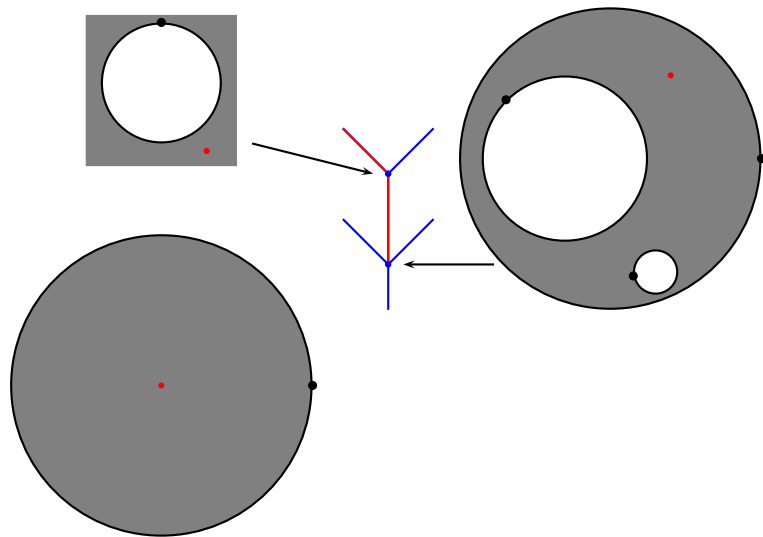
# Homotoping away the blue edges



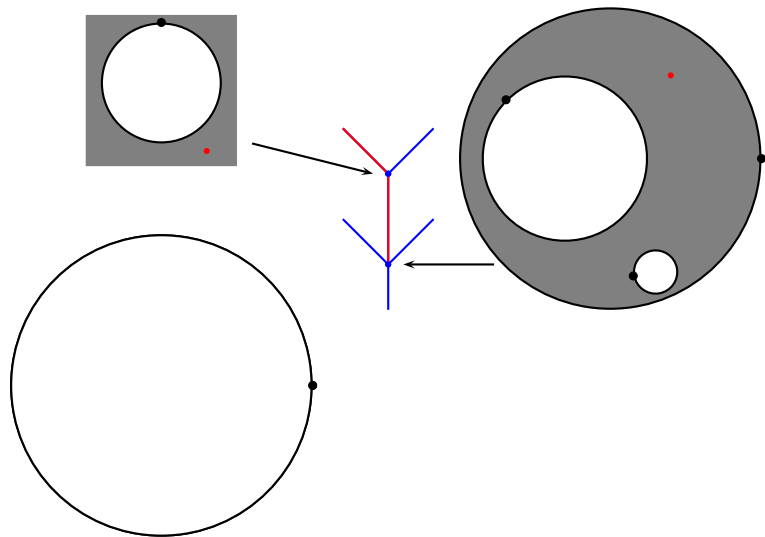
# Homotoping away the blue edges



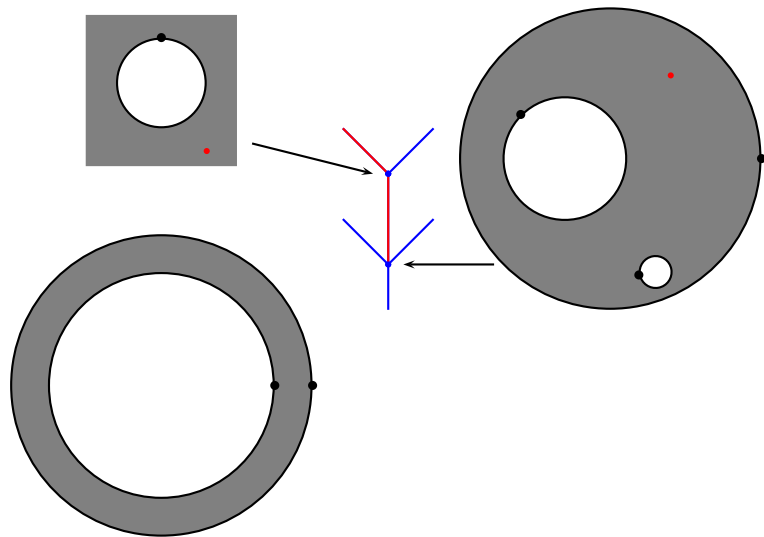
# Homotoping away the blue edges



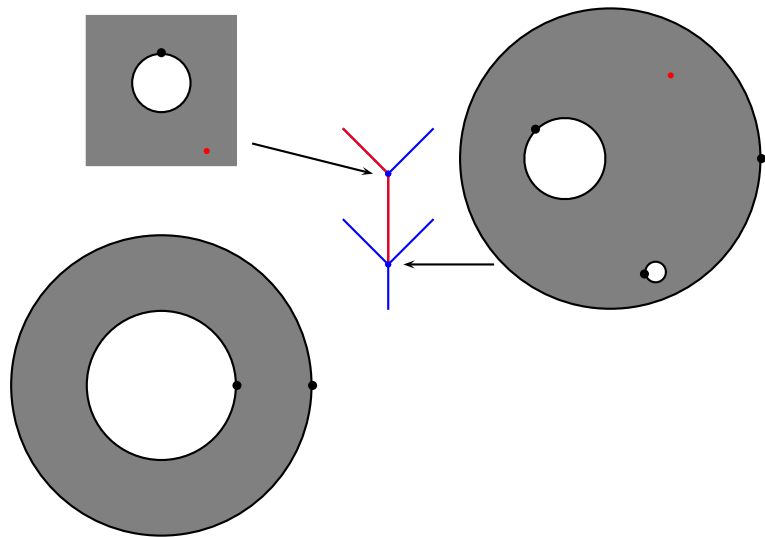
# Homotoping away the blue edges



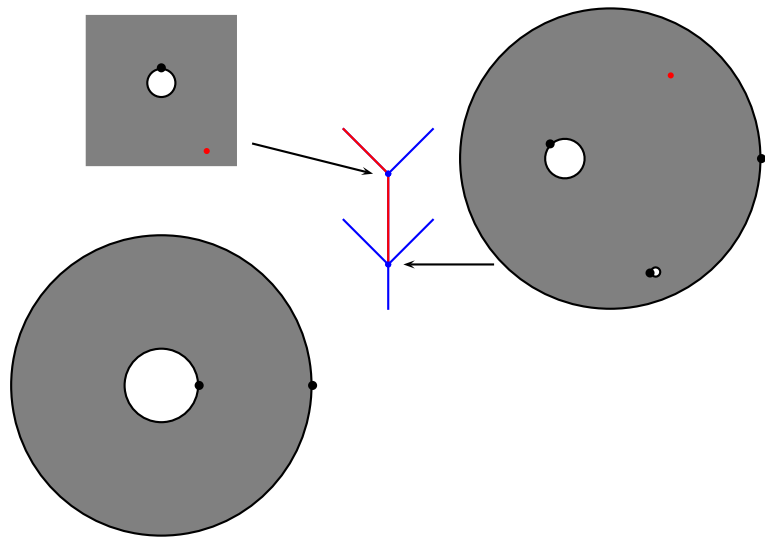
# Homotoping away the blue edges



# Homotoping away the blue edges

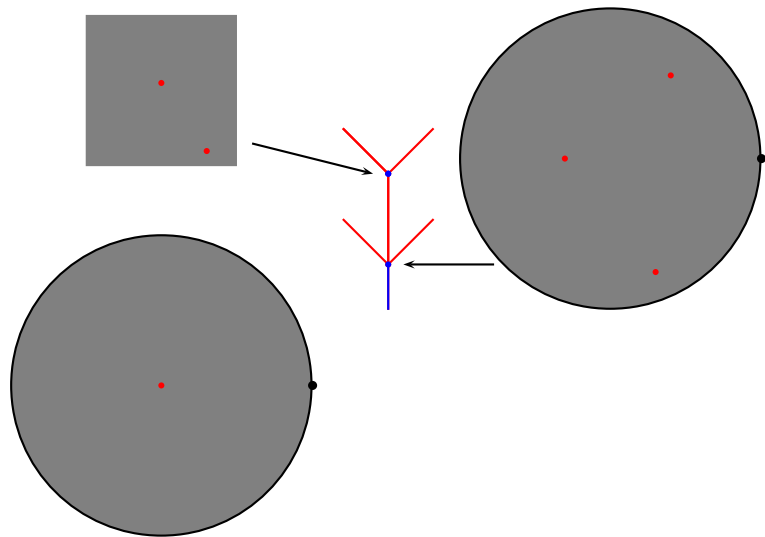


# Homotoping away the blue edges

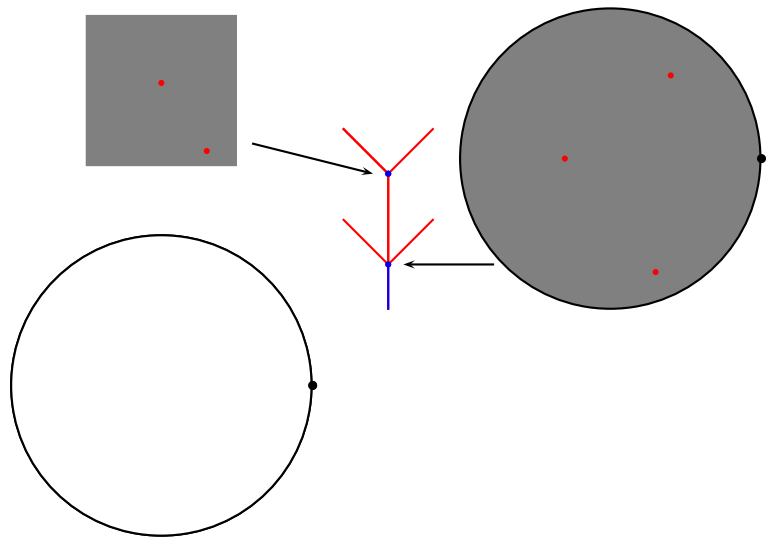




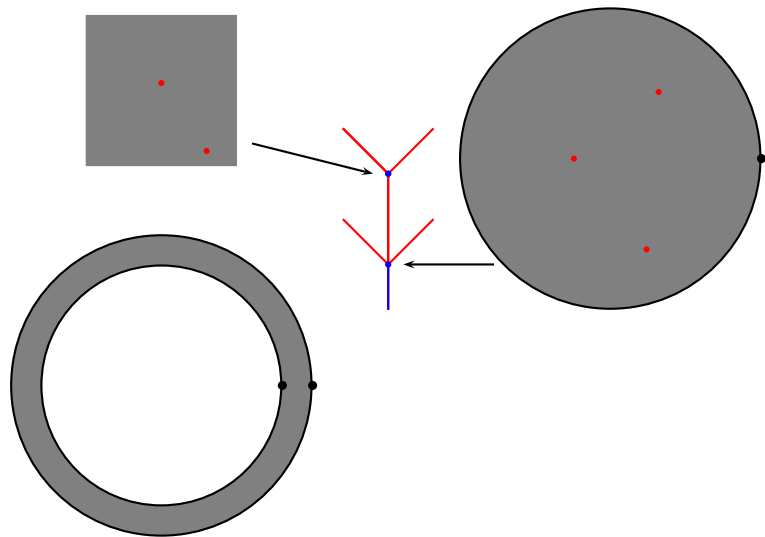
# Homotoping away the blue edges



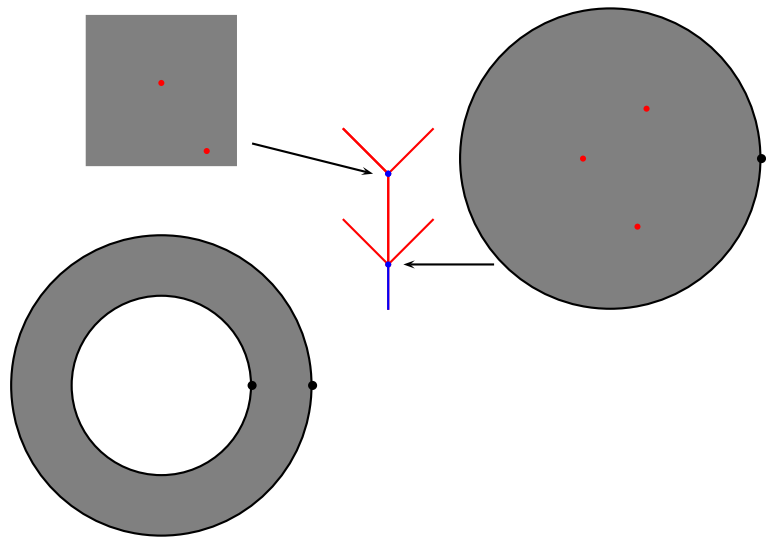
# Homotoping away the blue edges



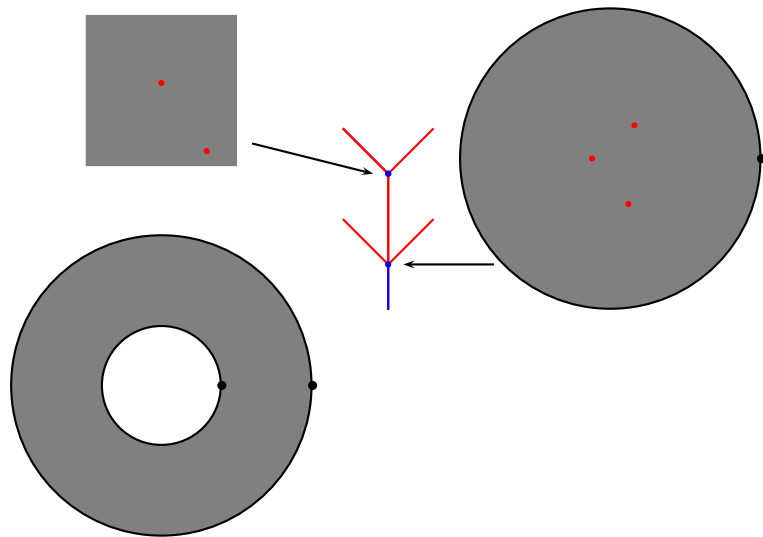
# Homotoping away the blue edges



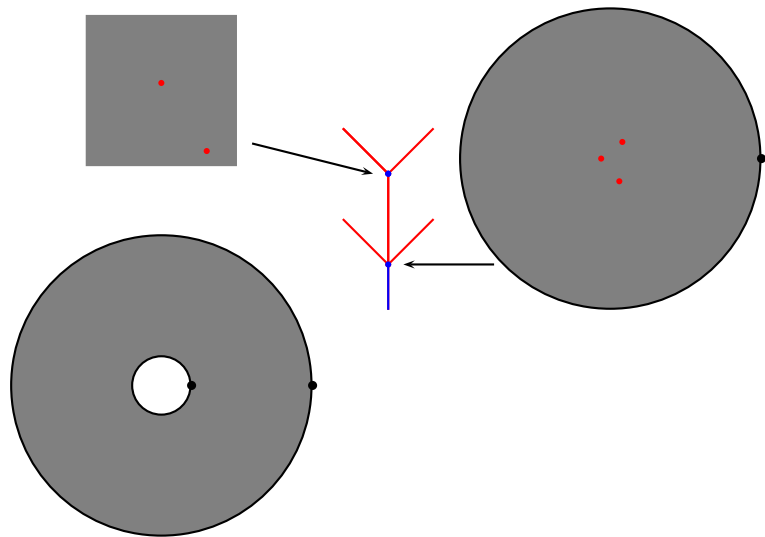
# Homotoping away the blue edges



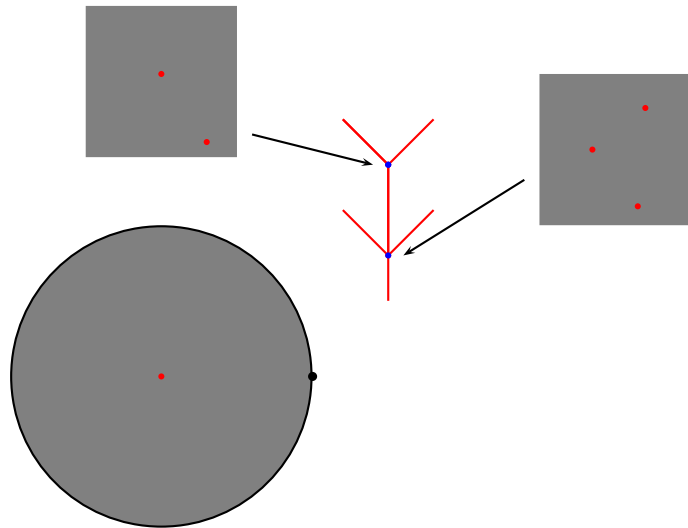
# Homotoping away the blue edges



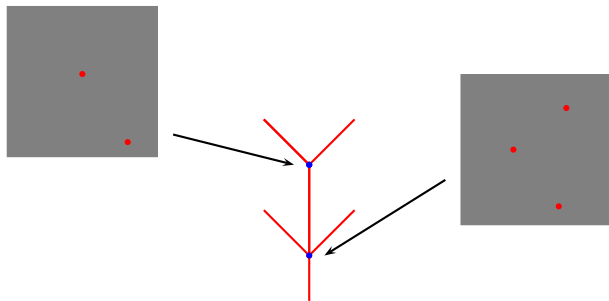
# Homotoping away the blue edges



# Homotoping away the blue edges



## Homotoping away the blue edges

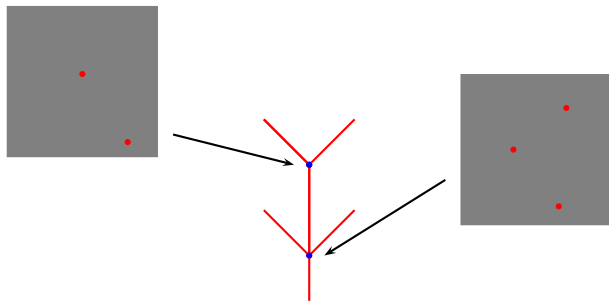


### Conclusion

$\overline{\mathcal{M}}(n)$  is a deformation retract of  $P_{\mathcal{M}}(n)$ .



## Homotoping away the blue edges



### Conclusion

$\overline{\mathcal{M}}(n)$  is a deformation retract of  $P_{\mathcal{M}}(n)$ .  
The map  $\overline{\mathcal{M}} \rightarrow P_{\mathcal{M}}$  is a map of operads.

# Describing $P_h$

Describing  $P_h = rFLD *_{S^1} tAn$

Describing  $P_h = rFLD *_{S^1} tAn$

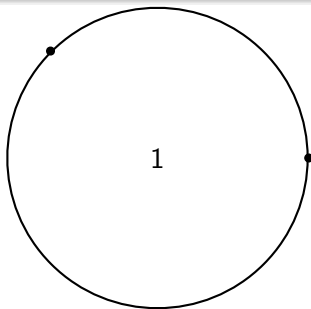
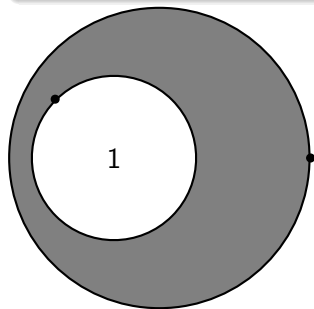
## Definition

$rFLD(n) = FLD(n)$ , except that

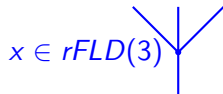
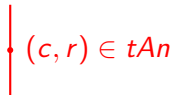
# Describing $P_h = rFLD *_{S^1} tAn$

## Definition

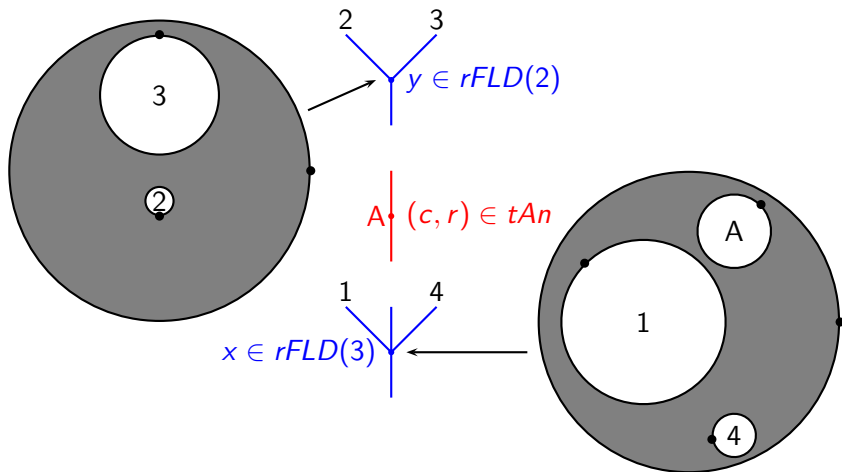
$rFLD(n) = FLD(n)$ , except that  $rFLD(1) = S^1$ .



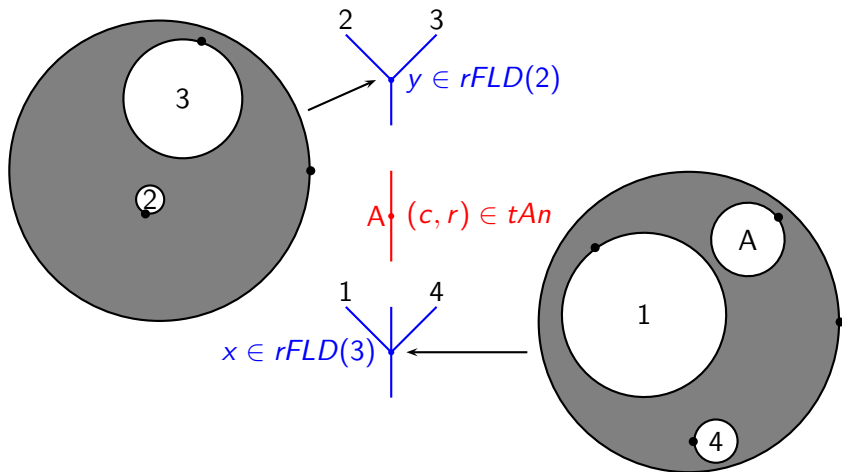
Describing  $P_h = rFLD *_{S^1} tAn$



# Describing $P_h = rFLD *_{S^1} tAn$

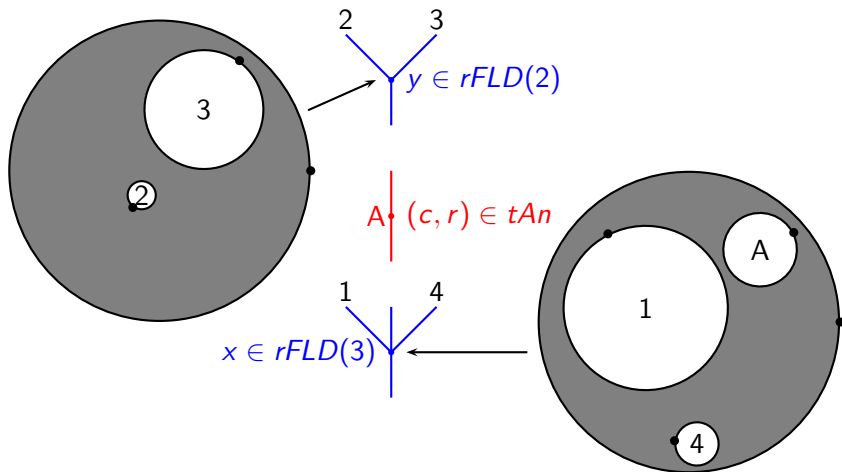


# Describing $P_h = rFLD *_{S^1} tAn$

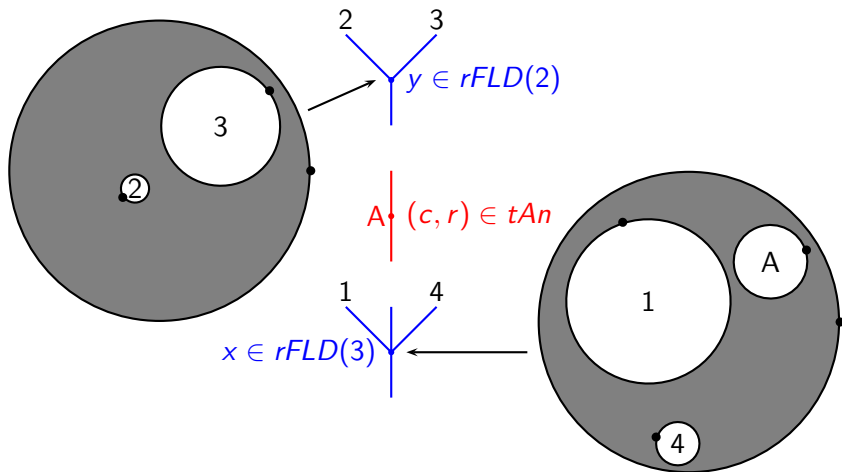




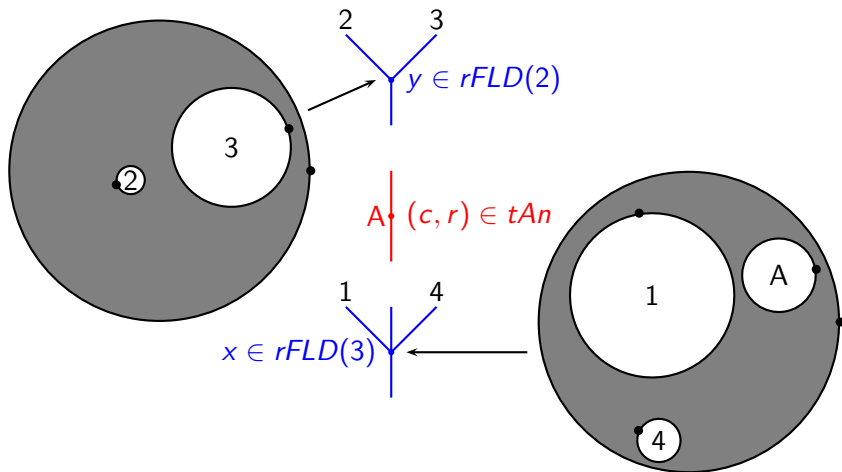
# Describing $P_h = rFLD *_{S^1} tAn$



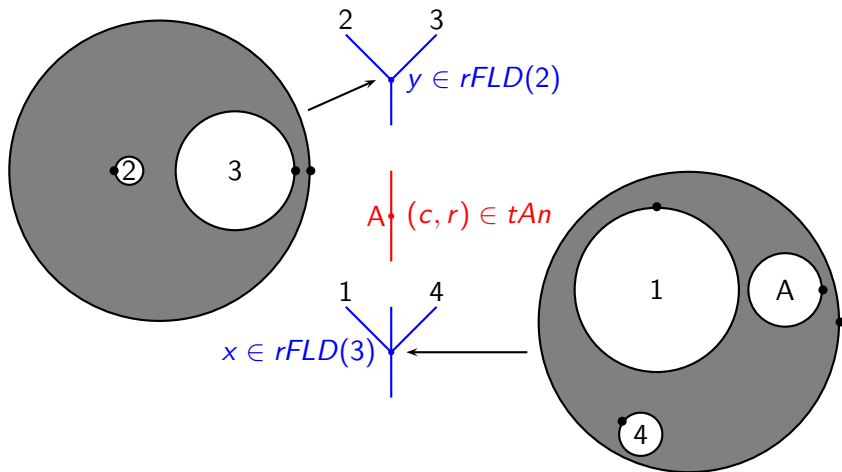
# Describing $P_h = rFLD *_{S^1} tAn$



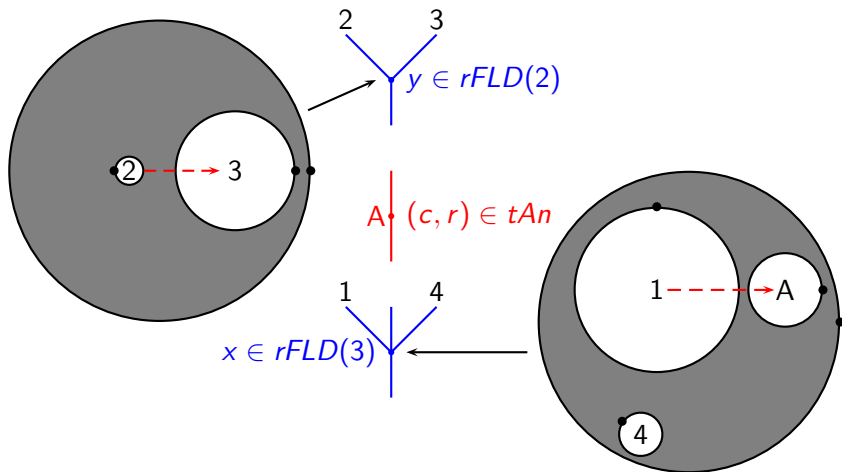
# Describing $P_h = rFLD *_{S^1} tAn$



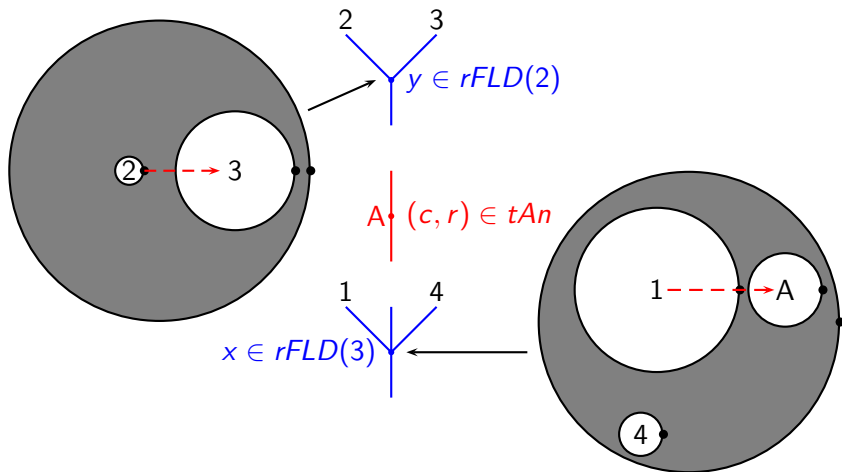
# Describing $P_h = rFLD *_{S^1} tAn$



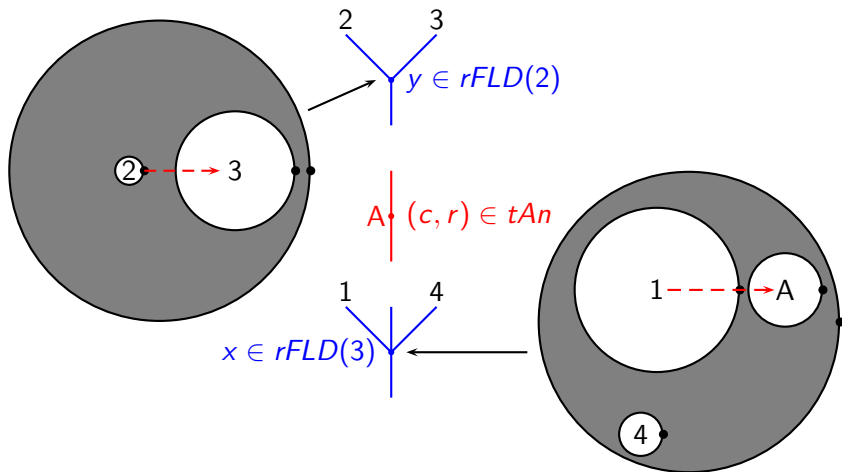
# Describing $P_h = rFLD *_{S^1} tAn$



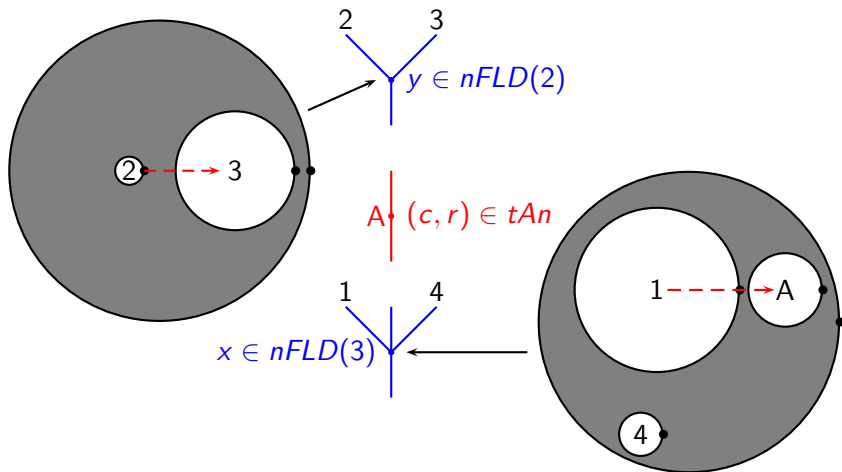
# Describing $P_h = rFLD *_{S^1} tAn$



# Describing $P_h = rFLD *_{S^1} tAn$

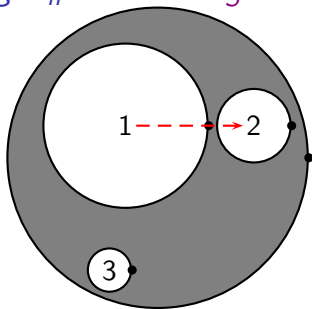


# Describing $P_h = rFLD *_{S^1} tAn$

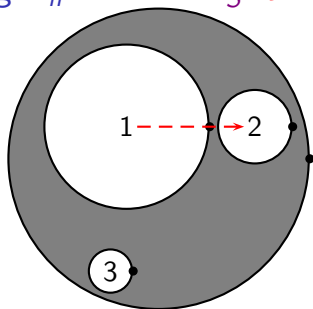




Describing  $P_h = rFLD *_{S^1} tAn$



Describing  $P_h = rFLD *_{S^1} tAn$



### Definition

$nFLD(n)$  consists of configurations of  $n$  framed little disks so that the vector from the center of the first disk to the center of the second disk, along with all of the radius vectors, are positive reals.

# Describing $P_h = rFLD *_{S^1} tAn$

## Definition

$nFLD(n)$  consists of configurations of  $n$  framed little disks so that the vector from the center of the first disk to the center of the second disk, along with all of the radius vectors, are positive reals.

## Observation

Every point in  $P_h$  can be realized “uniquely” as a tree with alternating bivalent and at least trivalent vertices, with markings on the bivalent vertices from  $tAn$  and on the other vertices from  $nFLD$ .

Showing  $P_h$  is a weak homotopy pushout

## Showing $P_h$ is a weak homotopy pushout

- The framed little disks  $FLD(n)$  are homeomorphic to the product  $S^1 \times nFLD(n) \times (S^1)^n$

## Showing $P_h$ is a weak homotopy pushout

- The framed little disks  $FLD(n)$  are homeomorphic to the product  $S^1 \times nFLD(n) \times (S^1)^n$
- The inclusion of the circle into the trivializable annuli is a pointed cofibration

## Showing $P_h$ is a weak homotopy pushout

- The framed little disks  $FLD(n)$  are homeomorphic to the product  $S^1 \times nFLD(n) \times (S^1)^n$
- The inclusion of the circle into the trivializable annuli is a pointed cofibration
- Weak equivalences and cofibrations of spaces interact nicely with coproducts and products

# Taking stock



# Taking stock

$$P_{\mathcal{M}} \overset{\sim}{\underset{\sim}{\rightleftarrows}} \overline{\mathcal{M}}$$

# Taking stock

$$P_h \quad P_{\mathcal{M}} \overset{\sim}{\underset{\sim}{\rightleftarrows}} \overline{\mathcal{M}}$$

# Taking stock

$$P_h \longrightarrow P_{\mathcal{M}} \begin{array}{c} \xrightarrow{\sim} \\ \xleftarrow{\sim} \end{array} \overline{\mathcal{M}}$$

# Taking stock

$$P_h \longrightarrow P_{\mathcal{M}} \xleftarrow[\sim]{\sim} \overline{\mathcal{M}}$$

$\tau$

# Taking stock

$$P_h \longrightarrow P_{\mathcal{M}} \xleftarrow[\sim]{\sim} \overline{\mathcal{M}}$$

$\tau$

## A criterion to show that a map is a weak equivalence

A map of spaces  $f$  is a weak equivalence if its range has an open cover, closed under finite intersection, and the restriction of  $f$  to each element of the cover is a weak equivalence.

# Taking stock

$$P_h \longrightarrow P_{\mathcal{M}} \xleftarrow{\sim} \overline{\mathcal{M}}$$

$\tau$

## A criterion to show that a map is a weak equivalence

A map of spaces  $f$  is a weak equivalence if its range has an open cover, closed under finite intersection, and the restriction of  $f$  to each element of the cover is a weak equivalence.

$U$

# Taking stock

$$P_h \longrightarrow P_{\mathcal{M}} \begin{array}{c} \xleftarrow{\sim} \\ \xrightarrow{\sim} \end{array} \overline{\mathcal{M}}$$

$\tau$

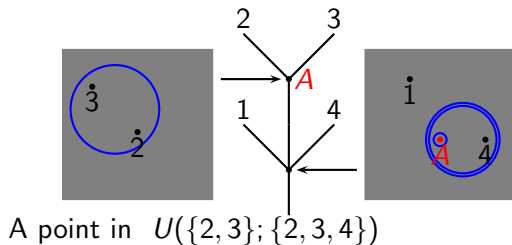
## A criterion to show that a map is a weak equivalence

A map of spaces  $f$  is a weak equivalence if its range has an open cover, closed under finite intersection, and the restriction of  $f$  to each element of the cover is a weak equivalence.

$$\tau^{-1}(U) \longrightarrow U$$

## Describing the local weak equivalence

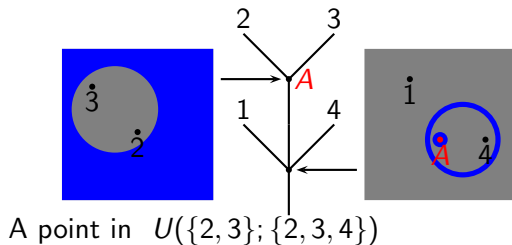
$U$  consists of configurations that can be simultaneously separated into certain partitions.





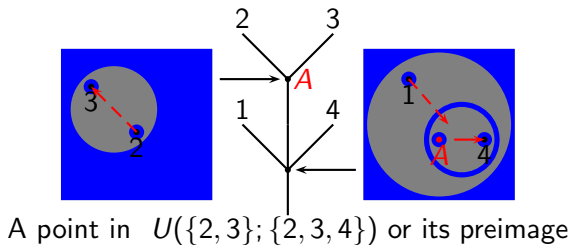
## Describing the local weak equivalence

$U$  consists of configurations that can be simultaneously separated into certain partitions.



## Describing the local weak equivalence

$U$  consists of configurations that can be simultaneously separated into certain partitions.

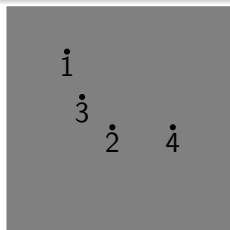
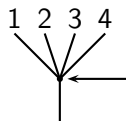


# Describing the local weak equivalence

$U$  consists of configurations that can be simultaneously separated into certain partitions.

## Simplifying assumptions

- Restrict to  $\mathcal{M}$  inside  $\overline{\mathcal{M}}$



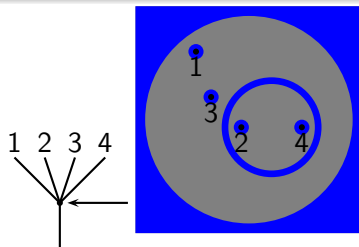
A point in  $U(\{2, 3\}; \{2, 3, 4\})$

# Describing the local weak equivalence

$U$  consists of configurations that can be simultaneously separated into certain partitions.

## Simplifying assumptions

- Restrict to  $\mathcal{M}$  inside  $\overline{\mathcal{M}}$
- Discard inappropriate separations in the preimage



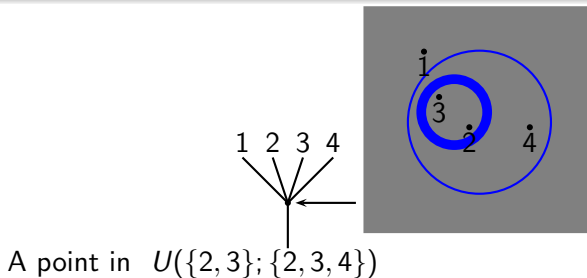
A point in the preimage of  $U(\{2, 3\}; \{2, 3, 4\})$

# Describing the local weak equivalence

$U$  consists of configurations that can be simultaneously separated into certain partitions.

## Simplifying assumptions

- Restrict to  $\mathcal{M}$  inside  $\overline{\mathcal{M}}$
- Discard inappropriate and ambiguous separations in the preimage

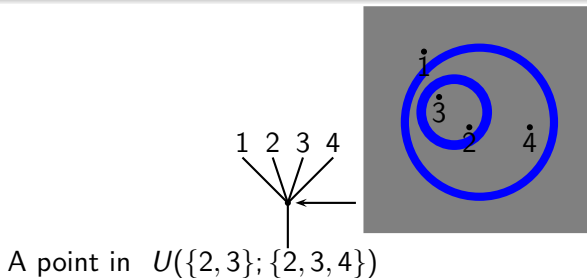


# Describing the local weak equivalence

$U$  consists of configurations that can be simultaneously separated into certain partitions.

## Simplifying assumptions

- Restrict to  $\mathcal{M}$  inside  $\overline{\mathcal{M}}$
- Discard inappropriate and ambiguous separations in the preimage
- This cover is not closed under finite intersection



# Justifying the restriction to $\mathcal{M}$

## Problem

It is not enough to achieve a weak equivalence on neighborhoods over  $\mathcal{M}$ ; these need to have appropriate limiting behavior at the boundary.

# Justifying the restriction to $\mathcal{M}$

## Problem

It is not enough to achieve a weak equivalence on neighborhoods over  $\mathcal{M}$ ; these need to have appropriate limiting behavior at the boundary.

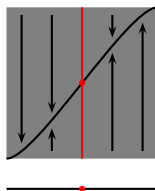




# Justifying the restriction to $\mathcal{M}$

## Problem

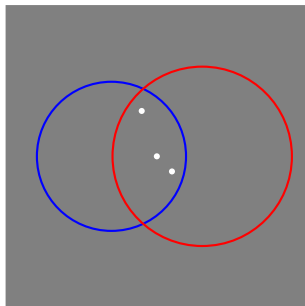
It is not enough to achieve a weak equivalence on neighborhoods over  $\mathcal{M}$ ; these need to have appropriate limiting behavior at the boundary.



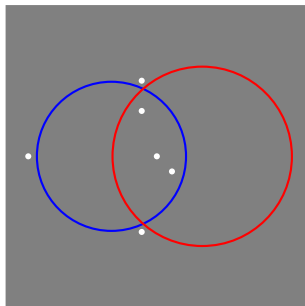
## Solution

Find a deformation retraction that is fixed fiberwise and that has appropriate limiting behavior.

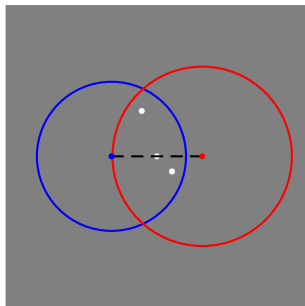
# Picturing the retraction



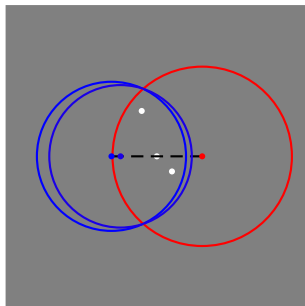
# Picturing the retraction



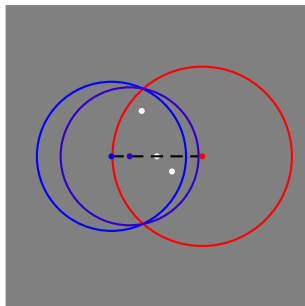
# Picturing the retraction



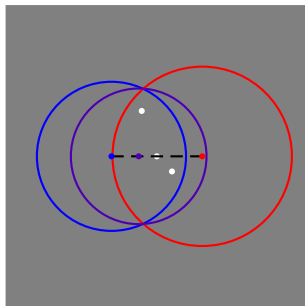
# Picturing the retraction



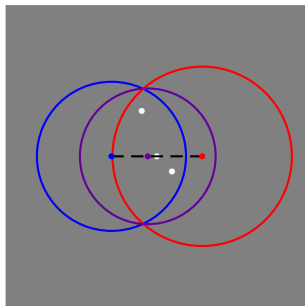
# Picturing the retraction



# Picturing the retraction

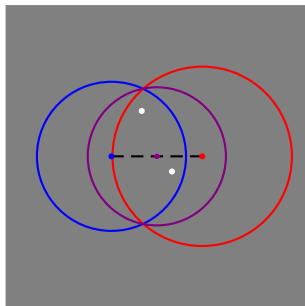


# Picturing the retraction

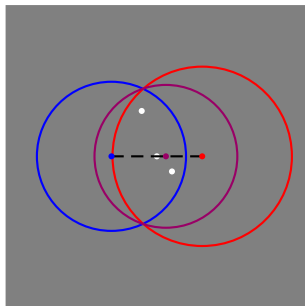




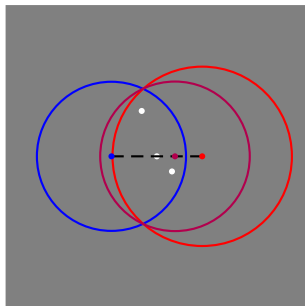
# Picturing the retraction



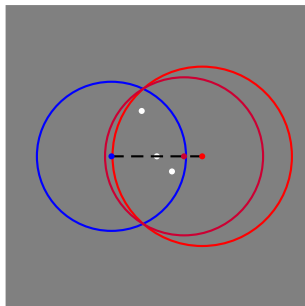
# Picturing the retraction



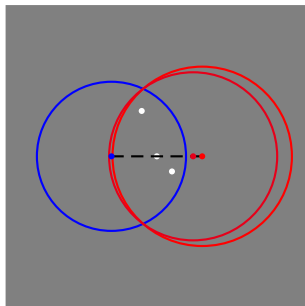
# Picturing the retraction



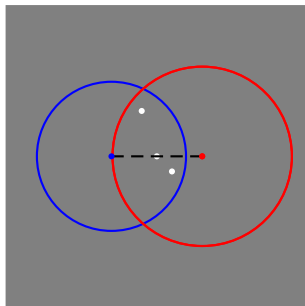
# Picturing the retraction



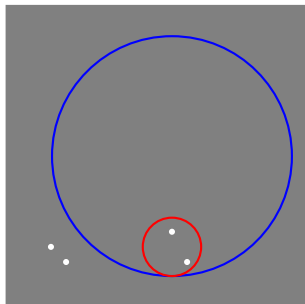
# Picturing the retraction



# Picturing the retraction

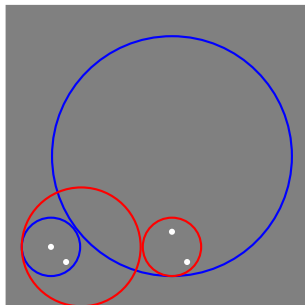


## Issues with the straight line homotopy



- Making sure disjoint pairs stay disjoint

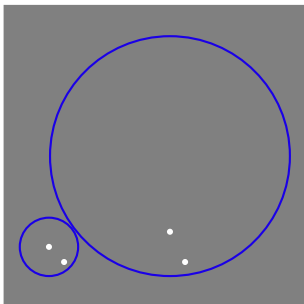
## Issues with the straight line homotopy



- Making sure disjoint pairs stay disjoint

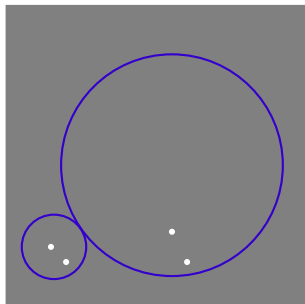


## Issues with the straight line homotopy



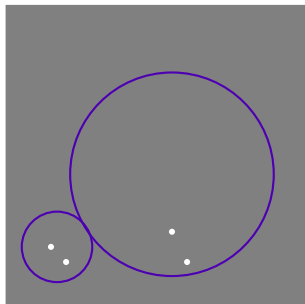
- Making sure disjoint pairs stay disjoint

## Issues with the straight line homotopy



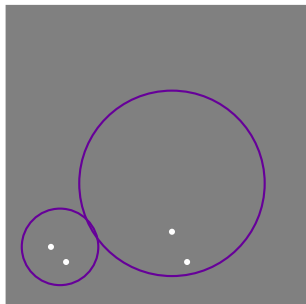
- Making sure disjoint pairs stay disjoint

## Issues with the straight line homotopy



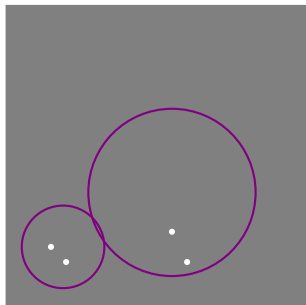
- Making sure disjoint pairs stay disjoint

## Issues with the straight line homotopy



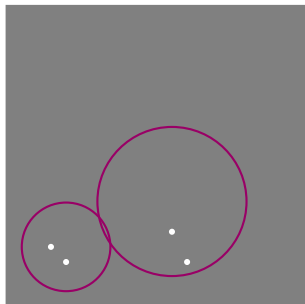
- Making sure disjoint pairs stay disjoint

## Issues with the straight line homotopy



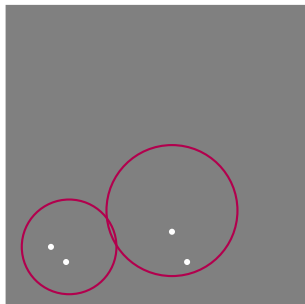
- Making sure disjoint pairs stay disjoint

## Issues with the straight line homotopy



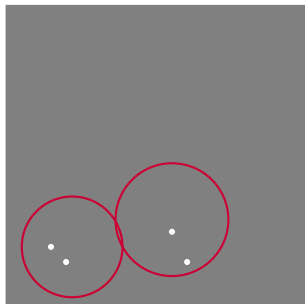
- Making sure disjoint pairs stay disjoint

## Issues with the straight line homotopy



- Making sure disjoint pairs stay disjoint

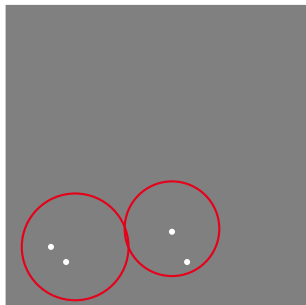
## Issues with the straight line homotopy



- Making sure disjoint pairs stay disjoint

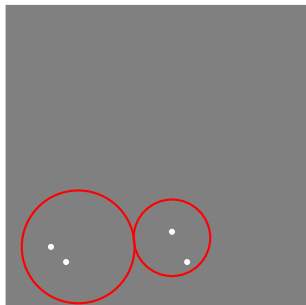


## Issues with the straight line homotopy



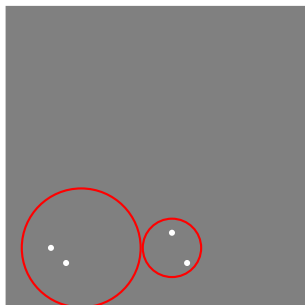
- Making sure disjoint pairs stay disjoint

## Issues with the straight line homotopy



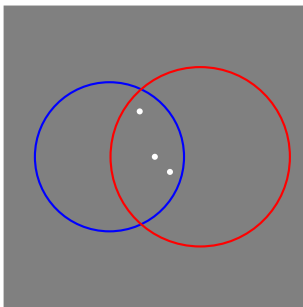
- Making sure disjoint pairs stay disjoint

## Issues with the straight line homotopy

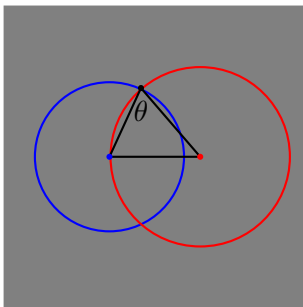


- Making sure disjoint pairs stay disjoint
- Making sure nested pairs stay nested

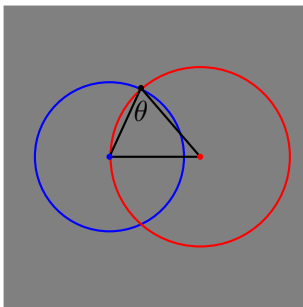
## A solution to the problem



## A solution to the problem

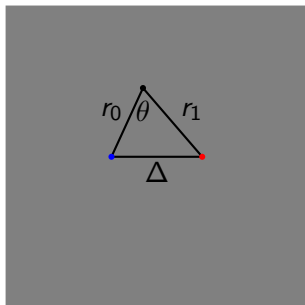


## A solution to the problem



Homotope through  $\theta$  rather than along the distance.

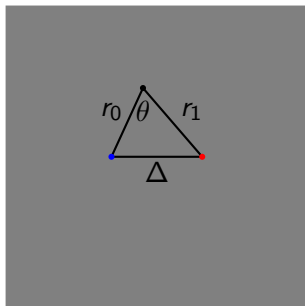
## A solution to the problem



Homotope through  $\theta$  rather than along the distance.

$$\theta = \arccos \left( \frac{r_0^2 + r_1^2 - \Delta^2}{2r_0r_1} \right)$$

## A solution to the problem



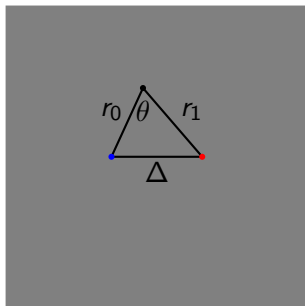
Homotope through  $\theta$  rather than along the distance.

$$\theta = \arccos \left( \frac{r_0^2 + r_1^2 - \Delta^2}{2r_0r_1} \right)$$

This formula makes sense as long as the radii are nonzero.  $\theta$  is either in  $[0, \pi)$  or is a positive imaginary number.



## A solution to the problem



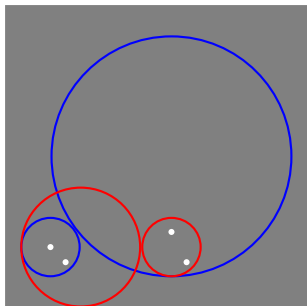
Homotope through  $\theta$  rather than along the distance.

$$\theta = \arccos \left( \frac{r_0^2 + r_1^2 - \Delta^2}{2r_0r_1} \right)$$

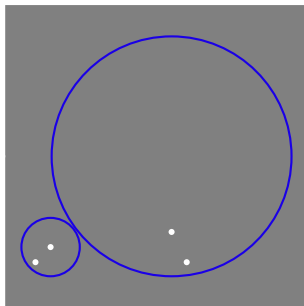
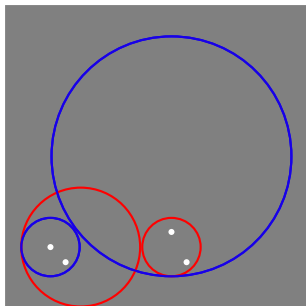
This formula makes sense as long as the radii are nonzero.  $\theta$  is either in  $[0, \pi)$  or is a positive imaginary number.

$$c_t = \frac{c_1 r_0 \sin(t\theta) + c_0 r_1 \sin((1-t)\theta)}{r_0 \sin(t\theta) + r_1 \sin((1-t)\theta)}, \quad r_t = \frac{r_0 r_1 \sin(\theta)}{r_0 \sin(t\theta) + r_1 \sin((1-t)\theta)}$$

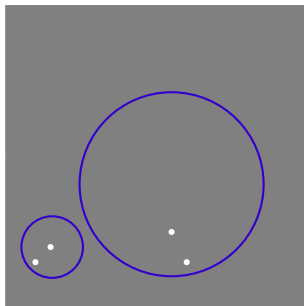
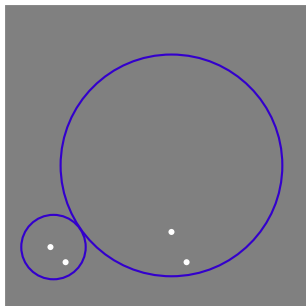
# Some evidence



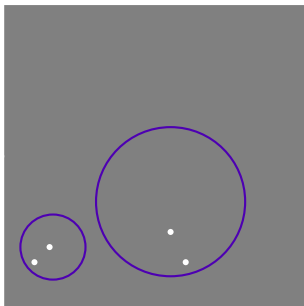
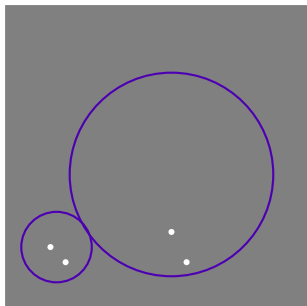
# Some evidence



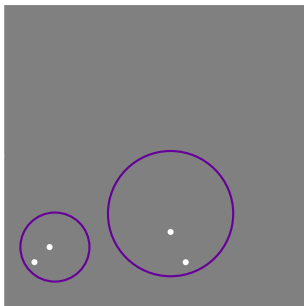
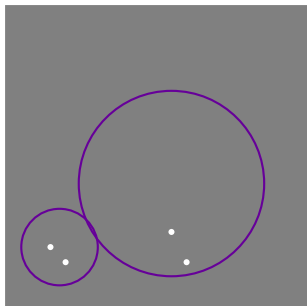
# Some evidence



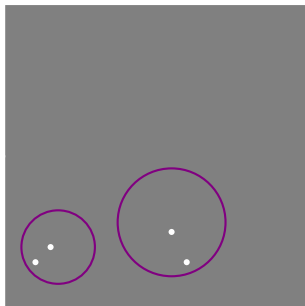
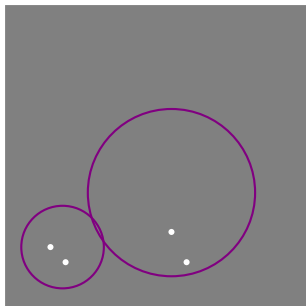
# Some evidence



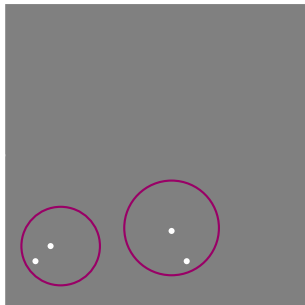
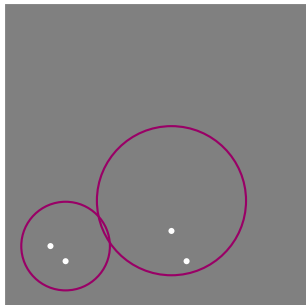
# Some evidence



# Some evidence

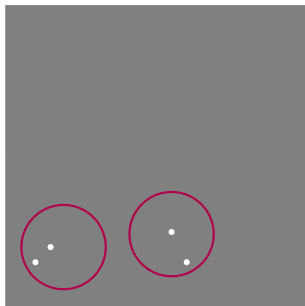
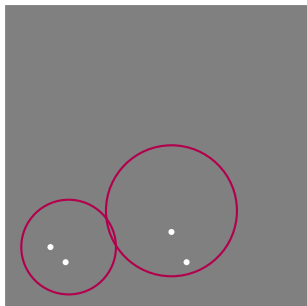


# Some evidence

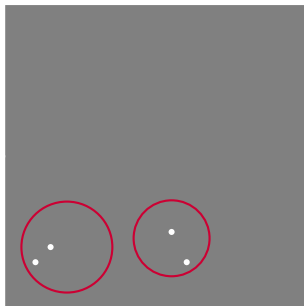
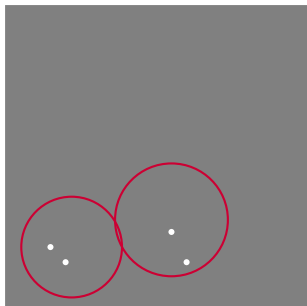




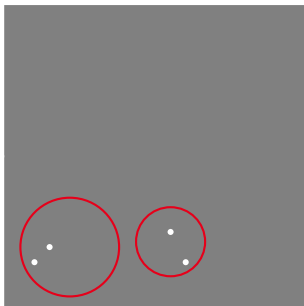
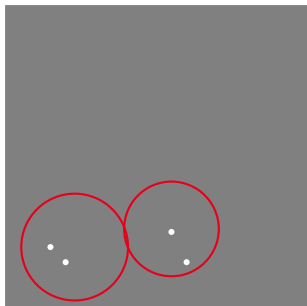
# Some evidence



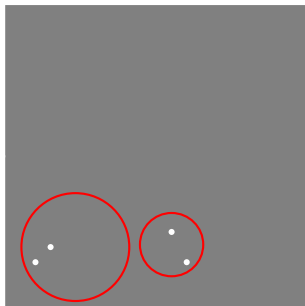
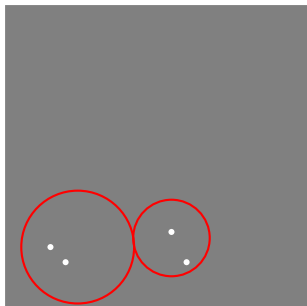
## Some evidence



# Some evidence



# Some evidence



## Some evidence

